## Vector calculus MA2VC 2013–14 — Assignment 3

Handed out: Friday 15th November. Due: Friday 29th November, 12 noon. Late assignments will not be accepted. Do not use red pen or pencil.

You can use formulas and identities from the lecture notes. Drawing a sketch of the domains may help you.

Total marks: 20. (5% of the total marks for the module.)

(1) (5 marks) Consider the unit square  $S = (0, 1)^2 = \{x\hat{i} + y\hat{j}, 0 < x < 1, 0 < y < 1\}$ and the triangle  $T = \{\xi\hat{\xi} + \eta\hat{\eta}, 0 < \xi < \eta < 1\}$  with vertices  $\vec{0}, \hat{\eta}$  and  $\hat{\xi} + \hat{\eta}$ .

(1a) Find a simple (bijective) change of variables  $(x, y) \mapsto (\xi, \eta)$  that maps S into T. Hint: consider a polynomial transformation that deforms the x variable only; in the notes you can find a (more complicated) example of a similar transformation.

(1b) Use the change of variables you found to compute

$$\iint_T \frac{\xi}{\eta} \,\mathrm{d}\xi \,\mathrm{d}\eta.$$

(2) (5 marks) Compute the volume of the domain D bounded by the unit cone  $\{x^2 + y^2 = z^2\}$  and the paraboloid  $\{z = x^2 + y^2\}$ , i.e.:

$$D = \{ \vec{\mathbf{r}} \in \mathbb{R}^3, \text{ s.t. } x^2 + y^2 < z < \sqrt{x^2 + y^2} \}.$$

Hint: find in Section 2.3 of the lecture notes a suitable system of coordinates to describe D.

(3) (5 marks) Consider the triangle R with vertices  $3\hat{i}$ ,  $2\hat{j}$  and  $\hat{k}$ . Fix on R the orientation  $\hat{n}$  such that  $\hat{n} \cdot \hat{k} > 0$ . Compute the flux of the vector field  $\vec{\mathbf{F}} = \vec{\mathbf{r}}$  through R.

Hint: consider R as the surface graph of a two-dimensional scalar field g(x, y).

Recall that, since R lies in a plane, the field g must be an affine function.

(4) (5 marks) State which of the following five expressions are well-defined and unambiguous; for those that are not, state precisely what does not work.

Consider only the notation used in the lecture notes and in class. Here  $\vec{\mathbf{F}}, \vec{\mathbf{G}}, \vec{\mathbf{H}} : \mathbb{R}^3 \to \mathbb{R}^3$ are smooth vector fields;  $f, g : \mathbb{R}^3 \to \mathbb{R}$  are smooth scalar fields;  $D \subset \mathbb{R}^3$  is a domain;  $\Gamma$  is an oriented path;  $\vec{\mathbf{a}}, \vec{\mathbf{b}} : \mathbb{R} \to \mathbb{R}^3$  are smooth curves. (As usual, in equations (a)-(d) all fields are evaluated in  $\vec{\mathbf{r}}$ , even if  $\vec{\mathbf{r}}$  is not explicitly written; e.g.  $\vec{\mathbf{F}} = \vec{\mathbf{F}}(\vec{\mathbf{r}})$ .)

(a) 
$$(\vec{\mathbf{r}} - |\vec{\mathbf{F}}|\vec{\mathbf{F}}) \cdot \left(\vec{\nabla} \times \left((F_1 + |\vec{\mathbf{F}}|^2 + F_3^3)\vec{\nabla} \cdot (\cos x\vec{\mathbf{F}} + \sin y\vec{\mathbf{G}} - 4\hat{j})\right) + \vec{\nabla}\left(fF_2 + e^g\frac{\partial F_1}{\partial z}\right)\right),$$

(b) 
$$\vec{\nabla}\Delta f + \left(\left(\vec{\nabla}\times\vec{\mathbf{F}}+\hat{\imath}\sqrt{|\vec{\mathbf{F}}|}\right)\cdot\vec{\nabla}\right)\vec{\mathbf{F}} - 5\int_{\Gamma}\left(\vec{\mathbf{F}}\times(\vec{\nabla}\times\vec{\mathbf{F}})+\vec{\nabla}\frac{\partial J}{\partial y}-\vec{\Delta}\vec{\mathbf{F}}\right)\cdot\mathrm{d}\vec{\mathbf{r}},$$
  
(c)  $\int \left(\int \left(\hat{\imath}\left(\vec{\mathbf{F}}\cdot\vec{\mathbf{G}}\times\vec{\mathbf{H}}+\cosh(\vec{\mathbf{F}}\cdot\vec{\mathbf{H}}-F_{1}H_{2}-F_{2}H_{1}\right))\vec{\nabla}f\right)\cdot\vec{\mathbf{r}}\,\mathrm{d}V + e^{\frac{1}{\pi}\sqrt{\int\int g\,\mathrm{d}V}}$ 

(c) 
$$\iiint_{D} \left( \hat{i} \left( \mathbf{F} \cdot \mathbf{G} \times \mathbf{H} + \cosh(\mathbf{F} \cdot \mathbf{H} - F_{1}H_{2} - F_{2}H_{1}) \right) \vee f \right) \cdot \vec{\mathbf{r}} \, \mathrm{d}V + e^{\pi \sqrt{JJ}D^{-1}V}$$
  
(d)  $\vec{\mathbf{F}} \vee \left( \hat{i} - \hat{\mathbf{r}} + \hat{\mathbf{F}} - \hat{\mathbf{F}} + \hat{\mathbf{F}$ 

(d) 
$$\vec{\mathbf{F}} \times \left( \hat{\boldsymbol{\imath}} \cos 3 + |\vec{\mathbf{F}} - 9\hat{\boldsymbol{\imath}}|^4 \hat{\boldsymbol{\jmath}} \times \left( \vec{\mathbf{G}} \cdot (\vec{\mathbf{H}} - \hat{\boldsymbol{\imath}}) \right) \vec{\mathbf{F}} \right) \times \left( \hat{\boldsymbol{\imath}} + 2\hat{\boldsymbol{\jmath}} + 3\hat{\boldsymbol{k}} \right) + \left( \vec{\mathbf{F}} \cdot \vec{\mathbf{G}} \right) \vec{\mathbf{F}} \times \vec{\mathbf{G}};$$

in equation (e) the dependences of <u>all</u> fields and curves are written explicitly  $(t \in \mathbb{R})$ :

(e) 
$$f\left(\vec{\mathbf{F}}\left(7\vec{\mathbf{a}}(t)\times\vec{\mathbf{b}}(t)\right)\right)e^{\vec{\mathbf{a}}(t)\cdot\hat{\mathbf{i}}-a_{2}(t)}\vec{\mathbf{G}}\left(\vec{\mathbf{a}}\left(\vec{\mathbf{G}}\left(\frac{d\vec{\mathbf{b}}}{dt}(t)\right)\cdot\vec{\mathbf{H}}\left(\vec{\mathbf{b}}(t)\right)\right)\right) + \vec{\mathbf{F}}\left(e^{|\vec{\mathbf{b}}(t)|^{2}}|\vec{\mathbf{a}}(t)\times\hat{\mathbf{k}}t|\right).$$