

Existence and long-time dynamics of a nonlocal Cahn-Hilliard-Navier-Stokes system with nonconstant mobility

E. Rocca

Università degli Studi di Milano

INTERFACES and Free Boundaries: ANALYSIS, Control and Simulation

Oberwolfach, 24 March - 30 March, 2013

joint preprint arXiv:1303.6446 with
Sergio Frigeri (Università di Milano) and Maurizio Grasselli (Politecnico di Milano)



Supported by the FP7-IDEAS-ERC-StG Grant "EntroPhase" #256872

Outline

Outline

- Introduce the **model H** - **diffuse interface** model for two phase fluids

Outline

- Introduce the **model H** - **diffuse interface** model for two phase fluids
- Investigate the mathematical meaning of **diffusion**

Outline

- Introduce the **model H - diffuse interface** model for two phase fluids
- Investigate the mathematical meaning of **diffusion**
- Introduce the **nonlocal model H** coupling
 - a nonlocal Cahn-Hilliard equation with nonconstant mobility
 - an incompressible Navier-Stokes system including the Korteweg force

Outline

- Introduce the **model H - diffuse interface** model for two phase fluids
- Investigate the mathematical meaning of **diffusion**
- Introduce the **nonlocal model H** coupling
 - a nonlocal Cahn-Hilliard equation with nonconstant mobility
 - an incompressible Navier-Stokes system including the Korteweg force
- Our main results on the **nonlocal model H**

Outline

- Introduce the **model H - diffuse interface** model for two phase fluids
- Investigate the mathematical meaning of **diffusion**
- Introduce the **nonlocal model H** coupling
 - a nonlocal Cahn-Hilliard equation with nonconstant mobility
 - an incompressible Navier-Stokes system including the Korteweg force
- Our main results on the **nonlocal model H**
 - ◊ **existence of solutions** in the 3D case for the nondegenerate and the **degenerate** mobility cases

Outline

- Introduce the **model H - diffuse interface** model for two phase fluids
- Investigate the mathematical meaning of **diffusion**
- Introduce the **nonlocal model H** coupling
 - a nonlocal Cahn-Hilliard equation with nonconstant mobility
 - an incompressible Navier-Stokes system including the Korteweg force
- Our main results on the **nonlocal model H**
 - ◇ **existence of solutions** in the 3D case for the nondegenerate and the **degenerate** mobility cases
 - ◇ **existence of the global attractor** (in the sense of generalized semiflows) in the 2D case

Outline

- Introduce the **model H - diffuse interface** model for two phase fluids
- Investigate the mathematical meaning of **diffusion**
- Introduce the **nonlocal model H** coupling
 - a nonlocal Cahn-Hilliard equation with nonconstant mobility
 - an incompressible Navier-Stokes system including the Korteweg force
- Our main results on the **nonlocal model H**
 - ◇ **existence of solutions** in the 3D case for the nondegenerate and the **degenerate** mobility cases
 - ◇ **existence of the global attractor** (in the sense of generalized semiflows) in the 2D case
- Our results on the 3D **convective nonlocal Cahn-Hilliard equation** with degenerate mobility

Outline

- Introduce the **model H - diffuse interface** model for two phase fluids
- Investigate the mathematical meaning of **diffusion**
- Introduce the **nonlocal model H** coupling
 - a nonlocal Cahn-Hilliard equation with nonconstant mobility
 - an incompressible Navier-Stokes system including the Korteweg force
- Our main results on the **nonlocal model H**
 - ◇ **existence of solutions** in the 3D case for the nondegenerate and the **degenerate** mobility cases
 - ◇ **existence of the global attractor** (in the sense of generalized semiflows) in the 2D case
- Our results on the 3D **convective nonlocal Cahn-Hilliard equation** with degenerate mobility
 - ◇ well-posedness
 - ◇ existence of the global attractor

Modelling motivation

- A well-known model which describes the evolution of an incompressible isothermal mixture of two immiscible fluids is the so-called **model H** (cf. [Gurtin, Polignone, Viñals, '96], [Hohenberg, Halperin, '77], [H. Abels' seminar])
- A fluid-mechanical theory for **two-phase mixtures of fluids** faces a well known mathematical difficulty:
 - ▶ the movement of the **interfaces** \implies **Lagrangian** description
 - ▶ the bulk fluid flow \implies **Eulerian** framework

Modelling motivation

- A well-known model which describes the evolution of an incompressible isothermal mixture of two immiscible fluids is the so-called **model H** (cf. [Gurtin, Polignone, Viñals, '96], [Hohenberg, Halperin, '77], [H. Abels' seminar])
- A fluid-mechanical theory for **two-phase mixtures of fluids** faces a well known mathematical difficulty:
 - ▶ the movement of the **interfaces** \implies **Lagrangian** description
 - ▶ the bulk fluid flow \implies **Eulerian** framework
- The **phase-field methods** overcome this problem by postulating the **existence of a “diffuse” interface** spread over a possibly narrow region covering the “real” sharp interface boundary:
 - ▶ an **order parameter** φ (concentration difference of the two components) is introduced to demarcate the two species and to indicate the location of the interface
 - ▶ mixing energy F is defined in terms of φ and its spatial gradient

Modelling motivation

- A well-known model which describes the evolution of an incompressible isothermal mixture of two immiscible fluids is the so-called **model H** (cf. [Gurtin, Polignone, Viñals, '96], [Hohenberg, Halperin, '77], [H. Abels' seminar])
- A fluid-mechanical theory for **two-phase mixtures of fluids** faces a well known mathematical difficulty:
 - ▶ the movement of the **interfaces** \implies **Lagrangian** description
 - ▶ the bulk fluid flow \implies **Eulerian** framework
- The **phase-field methods** overcome this problem by postulating the **existence of a “diffuse” interface** spread over a possibly narrow region covering the “real” sharp interface boundary:
 - ▶ an **order parameter** φ (concentration difference of the two components) is introduced to demarcate the two species and to indicate the location of the interface
 - ▶ mixing energy F is defined in terms of φ and its spatial gradient
- The time evolution of φ is described by means of a convection-diffusion equation: typically, different variants of **Cahn-Hilliard or Allen-Cahn** or other types of dynamics are used (see [Anderson et al., '98], [Feng, '06])

Modelling motivation

- A well-known model which describes the evolution of an incompressible isothermal mixture of two immiscible fluids is the so-called **model H** (cf. [Gurtin, Polignone, Viñals, '96], [Hohenberg, Halperin, '77], [H. Abels' seminar])
- A fluid-mechanical theory for **two-phase mixtures of fluids** faces a well known mathematical difficulty:
 - ▶ the movement of the **interfaces** \implies **Lagrangian** description
 - ▶ the bulk fluid flow \implies **Eulerian** framework
- The **phase-field methods** overcome this problem by postulating the **existence of a “diffuse” interface** spread over a possibly narrow region covering the “real” sharp interface boundary:
 - ▶ an **order parameter** φ (concentration difference of the two components) is introduced to demarcate the two species and to indicate the location of the interface
 - ▶ mixing energy F is defined in terms of φ and its spatial gradient
- The time evolution of φ is described by means of a convection-diffusion equation: typically, different variants of **Cahn-Hilliard or Allen-Cahn** or other types of dynamics are used (see [Anderson et al., '98], [Feng, '06])
- This parameter influences the (average) fluid velocity \mathbf{u} through a capillarity force (called **Korteweg force**) proportional to $\mu \nabla \varphi$, where μ is the chemical potential (cf. [Jasnow, Viñals, '96])

The local model H

The state variables are

- the order parameter φ
- the velocity field \mathbf{u}

The local model H

The state variables are

- the order parameter φ
- the velocity field \mathbf{u}

and the corresponding initial-boundary value problem (in $\Omega \times (0, T)$) is

$$\begin{aligned}\mathbf{u}_t - \nu \Delta \mathbf{u} + (\mathbf{u} \cdot \nabla) \mathbf{u} + \nabla \pi &= \mu \nabla \varphi + \mathbf{h}, & \operatorname{div}(\mathbf{u}) &= 0 \\ \varphi_t + \mathbf{u} \cdot \nabla \varphi &= \operatorname{div}(m(\varphi) \nabla \mu), & \mu &= -\sigma \Delta \varphi + \frac{1}{\sigma} F'(\varphi)\end{aligned}$$

where

- m denotes the non-constant mobility
- μ the chemical potential
- F the (density of) potential energy (logarithmic or double-well potential)
- $\mu \nabla \varphi$ is the so-called **Korteweg force**
- ν the viscosity and π the pressure
- $\sigma > 0$ is related to the (diffuse) interface thickness

Local and nonlocal Cahn-Hilliard

Local and nonlocal Cahn-Hilliard

The chemical potential μ represents the first variation of the free energy functionals:

Local and nonlocal Cahn-Hilliard

The chemical potential μ represents the first variation of the free energy functionals:

- (in the local case, cf. [Elliott, Garcke '96], [Boyer, '99], [Abels, '09], ...)

$$E(\varphi) = \int_{\Omega} \left(\frac{\sigma}{2} |\nabla \varphi(x)|^2 + \frac{F(\varphi(x))}{\sigma} \right) dx$$

Local and nonlocal Cahn-Hilliard

The chemical potential μ represents the first variation of the free energy functionals:

- (in the local case, cf. [Elliott, Garcke '96], [Boyer, '99], [Abels, '09], ...)

$$E(\varphi) = \int_{\Omega} \left(\frac{\sigma}{2} |\nabla \varphi(x)|^2 + \frac{F(\varphi(x))}{\sigma} \right) dx$$

- (in the nonlocal case, cf. [Gajewski, Zacharias, '03], ..., [Colli, Frigeri, Grasselli, '12])

$$E(\varphi) = \frac{1}{4} \int_{\Omega} \int_{\Omega} J(x-y) (\varphi(x) - \varphi(y))^2 dx dy + \int_{\Omega} \eta F(\varphi(x)) dx$$

- ▶ $J : \mathbb{R}^d \rightarrow \mathbb{R}$ is a smooth even function, e.g. $J(x) = j_3 |x|^{-1}$ in 3D and $J(x) = -j_2 \log |x|$ in 2D
- ▶ it is justified as a macroscopic limit of microscopic phase segregation models with particle conserving dynamics (cf. [Giacomin Lebowitz, '97&'98])

From Nonlocal to Local

Local Ginzburg-Landau potential “ \equiv ” $\lim_{\eta \rightarrow \infty}$ (Nonlocal van der Waals potential)

From Nonlocal to Local

Local Ginzburg-Landau potential “=” $\lim_{n \rightarrow \infty}$ **(Nonlocal van der Waals potential)**

Choosing $J(x, y) = n^{d+2} J(|n(x - y)|^2)$, with J nonnegative function supported in $[0, 1]$:

$$\int_{\Omega} n^{d+2} J(|n(x - y)|^2) |\varphi(x) - \varphi(y)|^2 dy = \int_{\Omega_n(x)} J(|z|^2) \left| \frac{\varphi(x + \frac{z}{n}) - \varphi(x)}{\frac{1}{n}} \right|^2 dz$$
$$\xrightarrow{n \rightarrow \infty} \int_{\mathbb{R}^d} J(|z|^2) \langle \nabla \varphi(x), z \rangle^2 dz = \frac{\sigma}{2} |\nabla \varphi(x)|^2$$

where we denote

- $\sigma = 2/d \int_{\mathbb{R}^d} J(|z|^2) |z|^2 dz$ and $\Omega_n(x) = n(\Omega - x)$ and we have used the identity
- $\int_{\mathbb{R}^d} J(|z|^2) \langle e, z \rangle^2 dz = 1/d \int_{\mathbb{R}^d} J(|z|^2) |z|^2 dz$ for every unit vector $e \in \mathbb{R}^d$

From Nonlocal to Local

Local Ginzburg-Landau potential “=” $\lim_{n \rightarrow \infty}$ **(Nonlocal van der Waals potential)**

Choosing $J(x, y) = n^{d+2} J(|n(x - y)|^2)$, with J nonnegative function supported in $[0, 1]$:

$$\int_{\mathbb{R}^d} n^{d+2} J(|n(x - y)|^2) |\varphi(x) - \varphi(y)|^2 dy = \int_{\Omega_n(x)} J(|z|^2) \left| \frac{\varphi\left(x + \frac{z}{n}\right) - \varphi(x)}{\frac{1}{n}} \right|^2 dz$$
$$\xrightarrow{n \rightarrow \infty} \int_{\mathbb{R}^d} J(|z|^2) \langle \nabla \varphi(x), z \rangle^2 dz = \frac{\sigma}{2} |\nabla \varphi(x)|^2$$

where we denote

- $\sigma = 2/d \int_{\mathbb{R}^d} J(|z|^2) |z|^2 dz$ and $\Omega_n(x) = n(\Omega - x)$ and we have used the identity
- $\int_{\mathbb{R}^d} J(|z|^2) \langle e, z \rangle^2 dz = 1/d \int_{\mathbb{R}^d} J(|z|^2) |z|^2 dz$ for every unit vector $e \in \mathbb{R}^d$

Big changes in the model and in the analysis:

- the fourth order equation becomes a second order equation \implies more chance to get separation property and uniqueness
- the analysis is more challenging due to the less regularity of φ and so of the Korteweg force $\mu \nabla \varphi$

From Nonlocal to Local

Local Ginzburg-Landau potential “=” $\lim_{n \rightarrow \infty}$ **(Nonlocal van der Waals potential)**

Choosing $J(x, y) = n^{d+2} J(|n(x - y)|^2)$, with J nonnegative function supported in $[0, 1]$:

$$\int_{\Omega} n^{d+2} J(|n(x - y)|^2) |\varphi(x) - \varphi(y)|^2 dy = \int_{\Omega_n(x)} J(|z|^2) \left| \frac{\varphi(x + \frac{z}{n}) - \varphi(x)}{\frac{1}{n}} \right|^2 dz$$
$$\xrightarrow{n \rightarrow \infty} \int_{\mathbb{R}^d} J(|z|^2) \langle \nabla \varphi(x), z \rangle^2 dz = \frac{\sigma}{2} |\nabla \varphi(x)|^2$$

where we denote

- $\sigma = 2/d \int_{\mathbb{R}^d} J(|z|^2) |z|^2 dz$ and $\Omega_n(x) = n(\Omega - x)$ and we have used the identity
- $\int_{\mathbb{R}^d} J(|z|^2) \langle e, z \rangle^2 dz = 1/d \int_{\mathbb{R}^d} J(|z|^2) |z|^2 dz$ for every unit vector $e \in \mathbb{R}^d$

Big changes in the model and in the analysis:

- the fourth order equation becomes a second order equation \implies more chance to get separation property and uniqueness
- the analysis is more challenging due to the less regularity of φ and so of the Korteweg force $\mu \nabla \varphi$

A philosophical question: is diffusion local or nonlocal?

Understand Diffusion by Nonlocality

By Louis Caffarelli, at the “Colloquium Magenes”, Pavia, March 20, 2013:

Understand Diffusion by Nonlocality

By Louis Caffarelli, at the “Colloquium Magenes”, Pavia, March 20, 2013:

*“Diffusion is a process where the variable under consideration, a particle density, a temperature, a population **tends to revert to its surrounding average.**”*

The diffusion equation

$$u_t - \Delta u = 0$$

*does not seem to say much about diffusion, unless we realize that **the “Laplacian” is in fact the limit of an averaging process.***

Understand Diffusion by Nonlocality

By Louis Caffarelli, at the “Colloquium Magenes”, Pavia, March 20, 2013:

“Diffusion is a process where the variable under consideration, a particle density, a temperature, a population tends to revert to its surrounding average.

The diffusion equation

$$u_t - \Delta u = 0$$

does not seem to say much about diffusion, unless we realize that **the “Laplacian” is in fact the limit of an averaging process.**

If we consider

$$\Delta u = \lim_{\epsilon \rightarrow 0} \frac{c_\epsilon}{|B_\epsilon(x)|} \int_{B_\epsilon(x)} (u(y) - u(x)) dy,$$

the density at the point x compares itself with its values in a tiny surrounding ball. The difference between the surrounding average and the value at x , properly scaled is the “Laplacian”.

If the set to which u compares itself is not shrunk to zero, the process is an integral diffusion. More generally, for a positive symmetric kernel, it can be

$$Lu(x) = \int J(x, y)(u(y) - u(x)) dy.”$$

Our main aim: deal with the case of Cahn-Hilliard equation with **non constant mobility** m and **nonlocal** phase dynamics (cf. [Giacomin Lebowitz, '97&'98])

Our main aim: deal with the case of Cahn-Hilliard equation with **non constant mobility** m and **nonlocal** phase dynamics (cf. [Giacomin Lebowitz, '97&'98])

The state variables are

- the order parameter φ
- the velocity field \mathbf{u}

Our main aim: deal with the case of Cahn-Hilliard equation with **non constant mobility** m and **nonlocal** phase dynamics (cf. [Giacomin Lebowitz, '97&'98])

The state variables are

- the order parameter φ
- the velocity field \mathbf{u}

and the corresponding initial-boundary value problem (in $\Omega \times (0, T)$) is

$$\varphi_t + \mathbf{u} \cdot \nabla \varphi = \operatorname{div}(m(\varphi) \nabla \mu)$$

$$\mu = a\varphi - J * \varphi + F'(\varphi)$$

$$\mathbf{u}_t - \nu \Delta \mathbf{u} + (\mathbf{u} \cdot \nabla) \mathbf{u} + \nabla \pi = \mu \nabla \varphi + \mathbf{h}, \quad \operatorname{div}(\mathbf{u}) = 0$$

$$\frac{\partial \mu}{\partial n} = 0, \quad \mathbf{u} = \mathbf{0} \quad \text{on } \partial \Omega \times (0, T)$$

$$\mathbf{u}(0) = \mathbf{u}_0, \quad \varphi(0) = \varphi_0 \quad \text{in } \Omega$$

where

- m denotes the non-constant **mobility**
- μ the chemical potential
- $(J * \varphi)(x) := \int_{\Omega} J(x-y)\varphi(y) dy$, $a(x) := \int_{\Omega} J(x-y) dy$, $x \in \Omega$ (**nonlocal operator**)
- F the (density of) **potential energy (logarithmic or double-well potential)**
- ν the viscosity and π the pressure

First part: The existence results

First part: The existence results

- The non degenerate mobility:

First part: The existence results

- The non degenerate mobility:
 - ▶ assumptions on m , J and F
 - ▶ *weak solution* notion
 - ▶ existence of weak solution and energy inequality (3D)/identity (2D)

First part: The existence results

- The non degenerate mobility:
 - ▶ assumptions on m , J and F
 - ▶ *weak solution* notion
 - ▶ existence of weak solution and energy inequality (3D)/identity (2D)
- The **degenerate mobility**:

First part: The existence results

- The non degenerate mobility:
 - ▶ assumptions on m , J and F
 - ▶ *weak solution* notion
 - ▶ existence of weak solution and energy inequality (3D)/identity (2D)
- The **degenerate mobility**:
 - ▶ assumptions on m and F
 - ▶ *weak solution* notion
 - ▶ existence of weak solution and **energetic inequality (3D)/identity (2D)**

The non degenerate mobility: assumptions

(H1) $m \in C_{loc}^{0,1}(\mathbb{R})$ and there exist $m_1, m_2 > 0$ such that $m_1 \leq m(s) \leq m_2$ for all $s \in \mathbb{R}$;

The non degenerate mobility: assumptions

(H1) $m \in C_{loc}^{0,1}(\mathbb{R})$ and there exist $m_1, m_2 > 0$ such that $m_1 \leq m(s) \leq m_2$ for all $s \in \mathbb{R}$;

(H2) $J(\cdot - x) \in W^{1,1}(\Omega)$ for a.a. $x \in \Omega$, $J(x) = J(-x)$, $a(x) := \int_{\Omega} J(x - y) dy \geq 0$ and

$$a^* := \sup_{x \in \Omega} \int_{\Omega} |J(x - y)| dy < \infty, \quad b := \sup_{x \in \Omega} \int_{\Omega} |\nabla J(x - y)| dy < \infty;$$

The non degenerate mobility: assumptions

(H1) $m \in C_{loc}^{0,1}(\mathbb{R})$ and there exist $m_1, m_2 > 0$ such that $m_1 \leq m(s) \leq m_2$ for all $s \in \mathbb{R}$;

(H2) $J(\cdot - x) \in W^{1,1}(\Omega)$ for a.a. $x \in \Omega$, $J(x) = J(-x)$, $a(x) := \int_{\Omega} J(x - y) dy \geq 0$ and

$$a^* := \sup_{x \in \Omega} \int_{\Omega} |J(x - y)| dy < \infty, \quad b := \sup_{x \in \Omega} \int_{\Omega} |\nabla J(x - y)| dy < \infty;$$

(H3) (quadratic perturbation of a strictly convex function) $F \in C_{loc}^{2,1}(\mathbb{R})$ and there exists $c_0 > 0$ such that

$$F''(s) + a(x) \geq c_0, \quad \forall s \in \mathbb{R}, \quad \text{a.e. } x \in \Omega;$$

(H4) There exist $c_1 > (a^* - a_*)/2$ ($a_* := \inf_{x \in \Omega} \int_{\Omega} J(x - y) dy$) and $c_2 \in \mathbb{R}$ such that

$$F(s) \geq c_1 s^2 - c_2, \quad \forall s \in \mathbb{R};$$

(H5) (fulfilled by arbitrary polynomially growing potentials) There exist $c_3 > 0$, $c_4 \geq 0$ and $r \in (1, 2]$ such that

$$|F'(s)|^r \leq c_3 |F(s)| + c_4, \quad \forall s \in \mathbb{R}$$

Definition 1: the non degenerate mobility – notion of weak solutions

Definition 1: the non degenerate mobility – notion of weak solutions

Let $u_0 \in (L^2(\Omega))_{div}$, $\varphi_0 \in L^2(\Omega)$ such that $F(\varphi_0) \in L^1(\Omega)$, $\mathbf{h} \in L^2(0, T; H^1(\Omega)_{div}^*)$, and $0 < T < \infty$ be given.

Definition 1: the non degenerate mobility – notion of weak solutions

Let $\mathbf{u}_0 \in (L^2(\Omega))_{div}$, $\varphi_0 \in L^2(\Omega)$ such that $F(\varphi_0) \in L^1(\Omega)$, $\mathbf{h} \in L^2(0, T; H^1(\Omega)_{div}^*)$, and $0 < T < \infty$ be given.

Then, a couple $[\mathbf{u}, \varphi]$ is a *weak solution* to the PDE system on $[0, T]$ if

$$\mathbf{u} \in L^\infty(0, T; L^2(\Omega)_{div}) \cap L^2(0, T; H^1(\Omega)_{div}), \quad \varphi \in L^\infty(0, T; L^2(\Omega)) \cap L^2(0, T; H^1(\Omega))$$

$$\mathbf{u}_t \in L^{4/3}(0, T; H^1(\Omega)_{div}^*), \quad \varphi_t \in L^{4/3}(0, T; H^1(\Omega)^*), \quad \text{if } d = 3,$$

$$\mathbf{u}_t \in L^{2-\gamma}(0, T; H^1(\Omega)_{div}^*), \quad \varphi_t \in L^{2-\delta}(0, T; H^1(\Omega)^*) \quad (\gamma, \delta \in (0, 1)), \quad \text{if } d = 2$$

$$\mu := a\varphi - J * \varphi + F'(\varphi) \in L^2(0, T; H^1(\Omega))$$

and the following variational formulation is satisfied for a.a. $t \in (0, T)$

$$\langle \varphi_t, \psi \rangle + (m(\varphi) \nabla \mu, \nabla \psi) = (\mathbf{u} \varphi, \nabla \psi), \quad \forall \psi \in H^1(\Omega)$$

$$\langle \mathbf{u}_t, \mathbf{v} \rangle + \nu(\nabla \mathbf{u}, \nabla \mathbf{v}) + b(\mathbf{u}, \mathbf{u}, \mathbf{v}) = -(\varphi \nabla \mu, \mathbf{v}) + \langle \mathbf{h}, \mathbf{v} \rangle, \quad \forall \mathbf{v} \in H^1(\Omega)_{div}$$

together with the initial conditions $\mathbf{u}(0) = \mathbf{u}_0$, $\varphi(0) = \varphi_0$ in Ω and where

$$b(\mathbf{u}, \mathbf{v}, \mathbf{w}) := \int_{\Omega} (\mathbf{u} \cdot \nabla) \mathbf{v} \cdot \mathbf{w}, \quad \forall \mathbf{u}, \mathbf{v}, \mathbf{w} \in H^1(\Omega)_{div}$$

Theorem 1: the non degenerate mobility – existence of solutions in 3D

Theorem 1: the non degenerate mobility – existence of solutions in 3D

Let $u_0 \in L^2(\Omega)_{div}$, $\varphi_0 \in L^2(\Omega)$ such that $F(\varphi_0) \in L^1(\Omega)$, $\mathbf{h} \in L^2(0, T; H^1(\Omega)_{div}^*)$, and suppose that (H1)-(H5) are satisfied.

Theorem 1: the non degenerate mobility – existence of solutions in 3D

Let $u_0 \in L^2(\Omega)_{div}$, $\varphi_0 \in L^2(\Omega)$ such that $F(\varphi_0) \in L^1(\Omega)$, $\mathbf{h} \in L^2(0, T; H^1(\Omega)_{div}^*)$, and suppose that (H1)-(H5) are satisfied. Then, for every given $T > 0$, there exists a weak solution $[u, \varphi]$ satisfying the **energy inequality**

$$\mathcal{E}(\mathbf{u}(t), \varphi(t)) + \int_0^t \left(\nu \|\nabla \mathbf{u}\|^2 + \|\sqrt{m(\varphi)} \nabla \mu\|^2 \right) d\tau \leq \mathcal{E}(\mathbf{u}_0, \varphi_0) + \int_0^t \langle \mathbf{h}(\tau), \mathbf{u} \rangle d\tau$$

for every $t > 0$, where we have set

$$\mathcal{E}(\mathbf{u}(t), \varphi(t)) = \frac{1}{2} \|\mathbf{u}(t)\|^2 + \frac{1}{4} \int_{\Omega} \int_{\Omega} J(x-y) (\varphi(x, t) - \varphi(y, t))^2 dx dy + \int_{\Omega} F(\varphi(t)) dx$$

Theorem 1: the non degenerate mobility – existence of solutions in 3D

Let $u_0 \in L^2(\Omega)_{div}$, $\varphi_0 \in L^2(\Omega)$ such that $F(\varphi_0) \in L^1(\Omega)$, $\mathbf{h} \in L^2(0, T; H^1(\Omega)_{div}^*)$, and suppose that (H1)-(H5) are satisfied. Then, for every given $T > 0$, there exists a weak solution $[u, \varphi]$ satisfying the **energy inequality**

$$\mathcal{E}(\mathbf{u}(t), \varphi(t)) + \int_0^t \left(\nu \|\nabla \mathbf{u}\|^2 + \|\sqrt{m(\varphi)} \nabla \mu\|^2 \right) d\tau \leq \mathcal{E}(\mathbf{u}_0, \varphi_0) + \int_0^t \langle \mathbf{h}(\tau), \mathbf{u} \rangle d\tau$$

for every $t > 0$, where we have set

$$\mathcal{E}(\mathbf{u}(t), \varphi(t)) = \frac{1}{2} \|\mathbf{u}(t)\|^2 + \frac{1}{4} \int_{\Omega} \int_{\Omega} J(x-y) (\varphi(x, t) - \varphi(y, t))^2 dx dy + \int_{\Omega} F(\varphi(t)) dx$$

Furthermore, assume that [(H4): $F(s) \geq c_1 s^2 - c_2$] is replaced by

(H7) (fulfilled by the classical double well) $F \in C_{loc}^{2,1}(\mathbb{R})$ and there exist $c_5 > 0$, $c_6 > 0$ and $p > 2$ such that

$$F''(s) + a(x) \geq c_5 |s|^{p-2} - c_6, \quad \forall s \in \mathbb{R}, \text{ a.e. } x \in \Omega, \quad a(x) := \int_{\Omega} J(x-y) dy$$

Theorem 1: the non degenerate mobility – existence of solutions in 3D

Let $u_0 \in L^2(\Omega)_{div}$, $\varphi_0 \in L^2(\Omega)$ such that $F(\varphi_0) \in L^1(\Omega)$, $\mathbf{h} \in L^2(0, T; H^1(\Omega)_{div}^*)$, and suppose that (H1)-(H5) are satisfied. Then, for every given $T > 0$, there exists a weak solution $[u, \varphi]$ satisfying the **energy inequality**

$$\mathcal{E}(\mathbf{u}(t), \varphi(t)) + \int_0^t \left(\nu \|\nabla \mathbf{u}\|^2 + \|\sqrt{m(\varphi)} \nabla \mu\|^2 \right) d\tau \leq \mathcal{E}(\mathbf{u}_0, \varphi_0) + \int_0^t \langle \mathbf{h}(\tau), \mathbf{u} \rangle d\tau$$

for every $t > 0$, where we have set

$$\mathcal{E}(\mathbf{u}(t), \varphi(t)) = \frac{1}{2} \|\mathbf{u}(t)\|^2 + \frac{1}{4} \int_{\Omega} \int_{\Omega} J(x-y) (\varphi(x, t) - \varphi(y, t))^2 dx dy + \int_{\Omega} F(\varphi(t)) dx$$

Furthermore, assume that [(H4): $F(s) \geq c_1 s^2 - c_2$] is replaced by

(H7) (fulfilled by the **classical double well**) $F \in C_{loc}^{2,1}(\mathbb{R})$ and there exist $c_5 > 0$, $c_6 > 0$ and $p > 2$ such that

$$F''(s) + a(x) \geq c_5 |s|^{p-2} - c_6, \quad \forall s \in \mathbb{R}, \text{ a.e. } x \in \Omega, \quad a(x) := \int_{\Omega} J(x-y) dy$$

Then, for every $T > 0$ there exists a weak solution $[u, \varphi]$ satisfying

$$\varphi \in L^\infty(0, T; L^p(\Omega)),$$

$$\varphi_t \in L^2(0, T; H^1(\Omega)^*), \quad \text{if } d = 2 \quad \text{or} \quad (d = 3 \text{ and } p \geq 3),$$

$$\mathbf{u}_t \in L^2(0, T; H^1(\Omega)_{div}^*), \quad \text{if } d = 2$$

The proof follows the line of [Colli, Frigeri, Grasselli, '12]

Theorem 1: The non degenerate mobility – existence of solutions in 2D

Theorem 1: The non degenerate mobility – existence of solutions in 2D

Assume that $d = 2$ and [(H4): $F(s) \geq c_1 s^2 - c_2$] is replaced by

(H7) $F \in C_{loc}^{2,1}(\mathbb{R})$ and there exist $c_5 > 0$, $c_6 > 0$ and $p > 2$ such that

$$F''(s) + a(x) \geq c_5 |s|^{p-2} - c_6, \quad \forall s \in \mathbb{R}, \quad \text{a.e. } x \in \Omega$$

Theorem 1: The non degenerate mobility – existence of solutions in 2D

Assume that $d = 2$ and [(H4): $F(s) \geq c_1 s^2 - c_2$] is replaced by

(H7) $F \in C_{loc}^{2,1}(\mathbb{R})$ and there exist $c_5 > 0$, $c_6 > 0$ and $p > 2$ such that

$$F''(s) + a(x) \geq c_5 |s|^{p-2} - c_6, \quad \forall s \in \mathbb{R}, \quad \text{a.e. } x \in \Omega$$

Then,

- any weak solution satisfies the **energy identity**

$$\frac{d}{dt} \mathcal{E}(\mathbf{u}, \varphi) + \nu \|\nabla \mathbf{u}\|^2 + \|\sqrt{m(\varphi)} \nabla \mu\|^2 = \langle \mathbf{h}(t), \mathbf{u} \rangle, \quad t > 0$$

Theorem 1: The non degenerate mobility – existence of solutions in 2D

Assume that $d = 2$ and [(H4): $F(s) \geq c_1 s^2 - c_2$] is replaced by

(H7) $F \in C_{loc}^{2,1}(\mathbb{R})$ and there exist $c_5 > 0$, $c_6 > 0$ and $p > 2$ such that

$$F''(s) + a(x) \geq c_5 |s|^{p-2} - c_6, \quad \forall s \in \mathbb{R}, \quad \text{a.e. } x \in \Omega$$

Then,

- any weak solution satisfies the **energy identity**

$$\frac{d}{dt} \mathcal{E}(\mathbf{u}, \varphi) + \nu \|\nabla \mathbf{u}\|^2 + \|\sqrt{m(\varphi)} \nabla \mu\|^2 = \langle \mathbf{h}(t), \mathbf{u} \rangle, \quad t > 0$$

In particular we have

$$\mathbf{u} \in C([0, \infty); L^2(\Omega)_{div}), \quad \varphi \in C([0, \infty); L^2(\Omega)), \quad \int_{\Omega} F(\varphi) \in C([0, \infty))$$

- If in addition $\mathbf{h} \in L_{tb}^2(0, \infty; H^1(\Omega)_{div}^*)$, then any weak solution satisfies also the **dissipative estimate**

$$\mathcal{E}(\mathbf{u}(t), \varphi(t)) \leq \mathcal{E}(\mathbf{u}_0, \varphi_0) e^{-kt} + F(m_0) |\Omega| + K, \quad \forall t \geq 0,$$

where $m_0 = (\varphi_0, 1)$ and k, K are two positive constants which are independent of the initial data, with K depending on Ω, ν, J, F and $\|\mathbf{h}\|_{L_{tb}^2(0, \infty; H^1(\Omega)_{div}^*)}$

The proof follows the line of [Colli, Frigeri, Grasselli, '12]

The degenerate mobility: assumptions

The degenerate mobility: assumptions

We shall now suppose that **the mobility m is degenerate** and that **the double-well potential F is singular in $(-1, 1)$** with 1 and -1 as singular points.

The degenerate mobility: assumptions

We shall now suppose that **the mobility m is degenerate** and that **the double-well potential F is singular in $(-1, 1)$** with 1 and -1 as singular points.

More precisely, we assume that (cf. [Elliott, Garcke, '96], [Gajewski, Zacharias, '03], [Giacomin, Lebowitz, '97&'98]) :

(D1) $m \in C^1([-1, 1])$, $m \geq 0$ and that $m(s) = 0$ if and only if $s = -1$ or $s = 1$,
 $F \in C^2(-1, 1)$ and

$$mF'' \in C([-1, 1])$$

The degenerate mobility: assumptions

We shall now suppose that **the mobility m is degenerate** and that **the double-well potential F is singular in $(-1, 1)$** with 1 and -1 as singular points.

More precisely, we assume that (cf. [Elliott, Garcke, '96], [Gajewski, Zacharias, '03], [Giacomin, Lebowitz, '97&'98]) :

- (D1)** $m \in C^1([-1, 1])$, $m \geq 0$ and that $m(s) = 0$ if and only if $s = -1$ or $s = 1$,
 $F \in C^2(-1, 1)$ and

$$mF'' \in C([-1, 1])$$

- (D2)** $F = F_1 + F_2$, $F_2 \in C^2([-1, 1])$ and there exists $a_2 > 4(a^* - a_* - b_2)$, where
 $b_2 = \min F_2''$ and $\varepsilon_0 > 0$ such that

$$F_1''(s) \geq a_2, \quad \forall s \in (-1, -1 + \varepsilon_0] \cup [1 - \varepsilon_0, 1)$$

- (D3)** There exists $\varepsilon_0 > 0$ such that F_1'' is non-decreasing in $[1 - \varepsilon_0, 1)$ and non-increasing in $(-1, -1 + \varepsilon_0]$

- (D4)** There exists $c_0 > 0$ such that

$$F''(s) + a(x) \geq c_0, \quad \forall s \in (-1, 1), \quad \text{a.e. } x \in \Omega$$

Examples of m and F

It is easy to see that (D1)–(D4) are satisfied in the physically relevant case where the mobility and the double-well potential are given by

$$m(s) = k_1(1 - s^2), \quad F(s) = -\frac{\theta_c}{2}s^2 + \frac{\theta}{2}((1 + s) \log(1 + s) + (1 - s) \log(1 - s))$$

where $0 < \theta < \theta_c$. Indeed, setting $F_1(s) := (\theta/2)((1 + s) \log(1 + s) + (1 - s) \log(1 - s))$ and $F_2(s) = -(\theta_c/2)s^2$, then we have

$$mF_1'' = k_1\theta > 0$$

and so (D1) is fulfilled, while (D4) holds if and only if $\inf_{\Omega} a > \theta_c - \theta$.

Examples of m and F

It is easy to see that (D1)–(D4) are satisfied in the physically relevant case where the mobility and the double-well potential are given by

$$m(s) = k_1(1 - s^2), \quad F(s) = -\frac{\theta_c}{2}s^2 + \frac{\theta}{2}((1 + s) \log(1 + s) + (1 - s) \log(1 - s))$$

where $0 < \theta < \theta_c$. Indeed, setting $F_1(s) := (\theta/2)((1 + s) \log(1 + s) + (1 - s) \log(1 - s))$ and $F_2(s) = -(\theta_c/2)s^2$, then we have

$$mF_1'' = k_1\theta > 0$$

and so (D1) is fulfilled, while (D4) holds if and only if $\inf_{\Omega} a > \theta_c - \theta$.

Another example is given by

$$m(s) = k(s)(1 - s^2)^m, \quad F(s) = -k_2s^2 + F_1(s)$$

where $k \in C^1([-1, 1])$ such that $0 < k_3 \leq k(s) \leq k_4$ for all $s \in [-1, 1]$, and F_1 is a $C^2(-1, 1)$ convex function such that

$$F_1''(s) = \ell(s)(1 - s^2)^{-m}, \quad \forall s \in (-1, 1)$$

where $m \geq 1$ and $\ell \in C^1([-1, 1])$

Definition 2: The degenerate mobility – notion of weak solutions

Definition 2: The degenerate mobility – notion of weak solutions

In the case the mobility degenerates **we are not able to control the gradient of the chemical potential μ in some L^p space** \implies we shall have to suitably reformulate a new definition of *weak solution* in such a way that μ does not appear any more

Definition 2: The degenerate mobility – notion of weak solutions

In the case the mobility degenerates **we are not able to control the gradient of the chemical potential μ in some L^p space** \implies we shall have to suitably reformulate a new definition of *weak solution* in such a way that μ does not appear any more

Let $u_0 \in L^2(\Omega)_{div}$, $\varphi_0 \in L^2(\Omega)$ with $F(\varphi_0) \in L^1(\Omega)$ and $0 < T < +\infty$ be given.

Definition 2: The degenerate mobility – notion of weak solutions

In the case the mobility degenerates **we are not able to control the gradient of the chemical potential μ in some L^p space** \implies we shall have to suitably reformulate a new definition of *weak solution* in such a way that μ does not appear any more

Let $u_0 \in L^2(\Omega)_{div}$, $\varphi_0 \in L^2(\Omega)$ with $F(\varphi_0) \in L^1(\Omega)$ and $0 < T < +\infty$ be given. A couple $[u, \varphi]$ is a *weak solution* on $[0, T]$ corresponding to $[u_0, \varphi_0]$ if

- \mathbf{u}, φ satisfy

$$\mathbf{u} \in L^\infty(0, T; L^2(\Omega)_{div}) \cap L^2(0, T; H^1(\Omega)_{div})$$

$$\mathbf{u}_t \in L^{4/3}(0, T; H^1(\Omega)_{div}^*) \text{ (if } d = 3), \mathbf{u}_t \in L^2(0, T; H^1(\Omega)_{div}^*) \text{ (if } d = 2)$$

$$\varphi \in L^\infty(0, T; L^2(\Omega)) \cap L^2(0, T; H^1(\Omega)), \varphi_t \in L^2(0, T; H^1(\Omega)^*)$$

$$\varphi \in L^\infty(Q_T), \quad |\varphi(x, t)| \leq 1 \quad \text{a.e. } (x, t) \in Q_T := \Omega \times (0, T)$$

- for every $\psi \in H^1(\Omega)$, every $\mathbf{v} \in H^1(\Omega)_{div}$ and for almost any $t \in (0, T)$ we have

$$\begin{aligned} \langle \varphi_t, \psi \rangle + \int_{\Omega} m(\varphi) F''(\varphi) \nabla \varphi \cdot \nabla \psi + \int_{\Omega} m(\varphi) a \nabla \varphi \cdot \nabla \psi \\ + \int_{\Omega} m(\varphi) (\varphi \nabla a - \nabla J * \varphi) \cdot \nabla \psi = \langle \mathbf{u} \varphi, \nabla \psi \rangle \end{aligned}$$

$$\langle \mathbf{u}_t, \mathbf{v} \rangle + \nu \langle \nabla \mathbf{u}, \nabla \mathbf{v} \rangle + b(\mathbf{u}, \mathbf{u}, \mathbf{v}) = \langle (a\varphi - J * \varphi) \nabla \varphi, \mathbf{v} \rangle + \langle \mathbf{h}, \mathbf{v} \rangle$$

$$\mathbf{u}(0) = \mathbf{u}_0, \varphi(0) = \varphi_0$$

Theorem 2: the degenerate mobility – existence of solutions

Introduce the function $M \in C^2(-1, 1)$ defined by $m(s)M''(s) = 1$, $M(0) = M'(0) = 0$

Assume (D1)–(D4), (H2). Let $\mathbf{h} \in L^2(0, T; H^1(\Omega)_{div}^*)$, $\mathbf{u}_0 \in L^2(\Omega)_{div}$, $\varphi_0 \in L^\infty(\Omega)$ such that $F(\varphi_0) \in L^1(\Omega)$ and $M(\varphi_0) \in L^1(\Omega)$

Theorem 2: the degenerate mobility – existence of solutions

Introduce the function $M \in C^2(-1, 1)$ defined by $m(s)M''(s) = 1$, $M(0) = M'(0) = 0$

Assume (D1)–(D4), (H2). Let $\mathbf{h} \in L^2(0, T; H^1(\Omega)_{div}^*)$, $\mathbf{u}_0 \in L^2(\Omega)_{div}$, $\varphi_0 \in L^\infty(\Omega)$ such that $F(\varphi_0) \in L^1(\Omega)$ and $M(\varphi_0) \in L^1(\Omega)$

Then, for every $T > 0$ there exists a *weak solution* $z := [\mathbf{u}, \varphi]$ on $[0, T]$ such that $\overline{\varphi}(t) = \overline{\varphi_0}$ for all $t \in [0, T]$ and $\varphi \in L^\infty(0, T; L^p(\Omega))$, where $p \leq 6$ for $d = 3$ and $2 \leq p < \infty$ for $d = 2$

Theorem 2: the degenerate mobility – existence of solutions

Introduce the function $M \in C^2(-1, 1)$ defined by $m(s)M''(s) = 1$, $M(0) = M'(0) = 0$

Assume (D1)–(D4), (H2). Let $\mathbf{h} \in L^2(0, T; H^1(\Omega)_{div}^*)$, $\mathbf{u}_0 \in L^2(\Omega)_{div}$, $\varphi_0 \in L^\infty(\Omega)$ such that $F(\varphi_0) \in L^1(\Omega)$ and $M(\varphi_0) \in L^1(\Omega)$

Then, for every $T > 0$ there exists a *weak solution* $z := [\mathbf{u}, \varphi]$ on $[0, T]$ such that $\overline{\varphi}(t) = \overline{\varphi_0}$ for all $t \in [0, T]$ and $\varphi \in L^\infty(0, T; L^p(\Omega))$, where $p \leq 6$ for $d = 3$ and $2 \leq p < \infty$ for $d = 2$

In addition, if $d = 2$, the weak solution $z := [\mathbf{u}, \varphi]$ satisfies the *the energetic equality*

$$\begin{aligned} & \frac{1}{2} \frac{d}{dt} (\|\mathbf{u}\|^2 + \|\varphi\|^2) + \int_{\Omega} m(\varphi) F''(\varphi) |\nabla \varphi|^2 + \int_{\Omega} a m(\varphi) |\nabla \varphi|^2 + \nu \|\nabla \mathbf{u}\|^2 \\ &= \int_{\Omega} m(\varphi) (\nabla J * \varphi - \varphi \nabla a) \cdot \nabla \varphi + \int_{\Omega} (a \varphi - J * \varphi) \mathbf{u} \cdot \nabla \varphi + \langle \mathbf{h}, \mathbf{u} \rangle \end{aligned}$$

Theorem 2: the degenerate mobility – existence of solutions

Introduce the function $M \in C^2(-1, 1)$ defined by $m(s)M''(s) = 1$, $M(0) = M'(0) = 0$

Assume (D1)–(D4), (H2). Let $\mathbf{h} \in L^2(0, T; H^1(\Omega)_{div}^*)$, $\mathbf{u}_0 \in L^2(\Omega)_{div}$, $\varphi_0 \in L^\infty(\Omega)$ such that $F(\varphi_0) \in L^1(\Omega)$ and $M(\varphi_0) \in L^1(\Omega)$

Then, for every $T > 0$ there exists a *weak solution* $z := [\mathbf{u}, \varphi]$ on $[0, T]$ such that $\overline{\varphi}(t) = \overline{\varphi_0}$ for all $t \in [0, T]$ and $\varphi \in L^\infty(0, T; L^p(\Omega))$, where $p \leq 6$ for $d = 3$ and $2 \leq p < \infty$ for $d = 2$

In addition, if $d = 2$, the weak solution $z := [\mathbf{u}, \varphi]$ satisfies the *the energetic equality*

$$\begin{aligned} & \frac{1}{2} \frac{d}{dt} (\|\mathbf{u}\|^2 + \|\varphi\|^2) + \int_{\Omega} m(\varphi) F''(\varphi) |\nabla \varphi|^2 + \int_{\Omega} am(\varphi) |\nabla \varphi|^2 + \nu \|\nabla \mathbf{u}\|^2 \\ &= \int_{\Omega} m(\varphi) (\nabla J * \varphi - \varphi \nabla a) \cdot \nabla \varphi + \int_{\Omega} (a\varphi - J * \varphi) \mathbf{u} \cdot \nabla \varphi + \langle \mathbf{h}, \mathbf{u} \rangle \end{aligned}$$

If $d = 3$ and if (H7) is satisfied with $p \geq 3$, z satisfies the following *energetic inequality*

$$\begin{aligned} & \frac{1}{2} (\|\mathbf{u}(t)\|^2 + \|\varphi(t)\|^2) + \int_0^t \int_{\Omega} m(\varphi) F''(\varphi) |\nabla \varphi|^2 + \int_0^t \int_{\Omega} am(\varphi) |\nabla \varphi|^2 \\ &+ \nu \int_0^t \|\nabla \mathbf{u}\|^2 \leq \frac{1}{2} (\|\mathbf{u}_0\|^2 + \|\varphi_0\|^2) + \int_0^t \int_{\Omega} m(\varphi) (\nabla J * \varphi - \varphi \nabla a) \cdot \nabla \varphi \\ &+ \int_0^t \int_{\Omega} (a\varphi - J * \varphi) \mathbf{u} \cdot \nabla \varphi + \int_0^t \langle \mathbf{h}, \mathbf{u} \rangle d\tau \quad \forall t > 0 \end{aligned}$$

An idea of the proof

An idea of the proof

- Approximate with a **regular potential** F_ε and a **non degenerate mobility** m_ε

An idea of the proof

- Approximate with a **regular potential** F_ε and a **non degenerate mobility** m_ε
- Due to **Theorem 1** we have an energy estimate:

$$\mathbf{u} \in L^\infty(0, T; L^2(\Omega)_{div}) \cap L^2(0, T; H^1(\Omega)_{div})$$

$$\varphi \in L^\infty(0, T; L^2(\Omega))$$

$$\sqrt{m} \nabla \mu \in L^2(0, T; L^2(\Omega))$$

An idea of the proof

- Approximate with a **regular potential** F_ε and a **non degenerate mobility** m_ε
- Due to **Theorem 1** we have an energy estimate:

$$\mathbf{u} \in L^\infty(0, T; L^2(\Omega)_{div}) \cap L^2(0, T; H^1(\Omega)_{div})$$

$$\varphi \in L^\infty(0, T; L^2(\Omega))$$

$$\sqrt{m} \nabla \mu \in L^2(0, T; L^2(\Omega))$$

- Take $\psi = M'(\varphi)$, where $m(s)M''(s) = 1$, $M(0) = M'(0) = 0$, in the approximated Cahn-Hilliard equation

$$\langle \varphi_t, \psi \rangle + (m(\varphi) \nabla \mu, \nabla \psi) = (\mathbf{u} \varphi, \nabla \psi)$$

getting from $\mu = a\varphi - J * \varphi + F'(\varphi)$ the term

$$\int_{\Omega} \left(m(\varphi) M''(\varphi) \nabla \mu \nabla \varphi = \int_{\Omega} (a + F''(\varphi)) |\nabla \varphi|^2 + \varphi \nabla a \nabla \varphi - \nabla J * \varphi \nabla \varphi \right) = 0$$

on the left hand side. Using the assumption: $a + F'' \geq c_0$, we get

$$\varphi \in L^2(0, T; H^1(\Omega))$$

An idea of the proof

- Approximate with a **regular potential** F_ε and a **non degenerate mobility** m_ε
- Due to **Theorem 1** we have an energy estimate:

$$\mathbf{u} \in L^\infty(0, T; L^2(\Omega)_{div}) \cap L^2(0, T; H^1(\Omega)_{div})$$

$$\varphi \in L^\infty(0, T; L^2(\Omega))$$

$$\sqrt{m} \nabla \mu \in L^2(0, T; L^2(\Omega))$$

- Take $\psi = M'(\varphi)$, where $m(s)M''(s) = 1$, $M(0) = M'(0) = 0$, in the approximated Cahn-Hilliard equation

$$\langle \varphi_t, \psi \rangle + (m(\varphi) \nabla \mu, \nabla \psi) = (\mathbf{u} \varphi, \nabla \psi)$$

getting from $\mu = a\varphi - J * \varphi + F'(\varphi)$ the term

$$\int_{\Omega} \left(m(\varphi) M''(\varphi) \nabla \mu \nabla \varphi = \int_{\Omega} (a + F''(\varphi)) |\nabla \varphi|^2 + \varphi \nabla a \nabla \varphi - \nabla J * \varphi \nabla \varphi \right) = 0$$

on the left hand side. Using the assumption: $a + F'' \geq c_0$, we get

$$\varphi \in L^2(0, T; H^1(\Omega))$$

- By comparison then we get in 3D

$$\varphi_t, \mu \nabla \varphi \in L^{4/3}(0, T; H^1(\Omega)^*) \text{ and so } \mathbf{u}_t \in L^{4/3}(0, T; H^1(\Omega)_{div}^*)$$

An idea of the proof

- Approximate with a **regular potential** F_ε and a **non degenerate mobility** m_ε
- Due to **Theorem 1** we have an energy estimate:

$$\mathbf{u} \in L^\infty(0, T; L^2(\Omega)_{div}) \cap L^2(0, T; H^1(\Omega)_{div})$$

$$\varphi \in L^\infty(0, T; L^2(\Omega))$$

$$\sqrt{m} \nabla \mu \in L^2(0, T; L^2(\Omega))$$

- Take $\psi = M'(\varphi)$, where $m(s)M''(s) = 1$, $M(0) = M'(0) = 0$, in the approximated Cahn-Hilliard equation

$$\langle \varphi_t, \psi \rangle + (m(\varphi) \nabla \mu, \nabla \psi) = (\mathbf{u} \varphi, \nabla \psi)$$

getting from $\mu = a\varphi - J * \varphi + F'(\varphi)$ the term

$$\int_{\Omega} \left(m(\varphi) M''(\varphi) \nabla \mu \nabla \varphi = \int_{\Omega} (a + F''(\varphi)) |\nabla \varphi|^2 + \varphi \nabla a \nabla \varphi - \nabla J * \varphi \nabla \varphi \right) = 0$$

on the left hand side. Using the assumption: $a + F'' \geq c_0$, we get

$$\varphi \in L^2(0, T; H^1(\Omega))$$

- By comparison then we get in 3D

$$\varphi_t, \mu \nabla \varphi \in L^{4/3}(0, T; H^1(\Omega)^*) \text{ and so } \mathbf{u}_t \in L^{4/3}(0, T; H^1(\Omega)_{div}^*)$$

- We pass to the limit as $\varepsilon \searrow 0$ obtaining the **weak formulation** stated in Theorem 2

Theorem 3: The case of strongly degenerate mobility

Assume, in addition to the previous hypotheses, that $m'(1) = m'(-1) = 0$

Theorem 3: The case of strongly degenerate mobility

Assume, in addition to the previous hypotheses, that $m'(1) = m'(-1) = 0$

Then, the weak solution $z = [\mathbf{u}, \varphi]$ fulfills also the following integral inequality

$$\mathcal{E}(z(t)) + \int_0^t \left(\nu \|\nabla \mathbf{u}\|^2 + \left\| \frac{\mathcal{J}}{\sqrt{m(\varphi)}} \right\|^2 \right) d\tau \leq \mathcal{E}(z_0) + \int_0^t \langle \mathbf{h}, \mathbf{u} \rangle d\tau$$

for all $t > 0$, where the **mass flux** \mathcal{J} is such that

$$\mathcal{J} \in L^2(Q_T), \quad \frac{\mathcal{J}}{\sqrt{m(\varphi)}} \in L^2(Q_T)$$

and is given by

$$\mathcal{J} = -m(\varphi)\nabla(a\varphi - J * \varphi) - m(\varphi)F''(\varphi)\nabla\varphi$$

Theorem 3: The case of strongly degenerate mobility

Assume, in addition to the previous hypotheses, that $m'(1) = m'(-1) = 0$

Then, the weak solution $z = [\mathbf{u}, \varphi]$ fulfills also the following integral inequality

$$\mathcal{E}(z(t)) + \int_0^t \left(\nu \|\nabla \mathbf{u}\|^2 + \left\| \frac{\mathcal{J}}{\sqrt{m(\varphi)}} \right\|^2 \right) d\tau \leq \mathcal{E}(z_0) + \int_0^t \langle \mathbf{h}, \mathbf{u} \rangle d\tau$$

for all $t > 0$, where the **mass flux** \mathcal{J} is such that

$$\mathcal{J} \in L^2(Q_T), \quad \frac{\mathcal{J}}{\sqrt{m(\varphi)}} \in L^2(Q_T)$$

and is given by

$$\mathcal{J} = -m(\varphi)\nabla(a\varphi - J * \varphi) - m(\varphi)F''(\varphi)\nabla\varphi$$

Note that in this case it can be proved that **the sets** $\{x \in \Omega : \varphi(x, t) = 1\}$ **and** $\{x \in \Omega : \varphi(x, t) = -1\}$ **have both measure zero** for a.a. $t > 0$

A comparison with the case of constant mobility

A comparison with the case of constant mobility

- Theorem 2, in comparison with the analogous result for the case of constant mobility (cf. [Frigeri, Grasselli, '12]) **does not require the condition** $|\bar{\varphi}_0| < 1!!$

A comparison with the case of constant mobility

- Theorem 2, in comparison with the analogous result for the case of constant mobility (cf. [Frigeri, Grasselli, '12]) **does not require the condition** $|\bar{\varphi}_0| < 1!!$
- The assumptions on φ_0 imply only the **less strict condition** $|\bar{\varphi}_0| \leq 1$
- This is due due to the **different weak solution formulation** with respect to the case of constant mobility

A comparison with the case of constant mobility

- Theorem 2, in comparison with the analogous result for the case of constant mobility (cf. [Frigeri, Grasselli, '12]) **does not require the condition** $|\bar{\varphi}_0| < 1!!$
- The assumptions on φ_0 imply only the **less strict condition** $|\bar{\varphi}_0| \leq 1$
- This is due due to the **different weak solution formulation** with respect to the case of constant mobility
- Therefore, if F is bounded (e.g. F is the logarithmic potential) and at $t = 0$ the fluid is in a pure phase, i.e. $\varphi_0 = 1$ a.e. in Ω , and furthermore $\mathbf{u}_0 = \mathbf{u}(0)$ is given in $L^2(\Omega)_{div}$, then the couple

$$\mathbf{u} = \mathbf{u}(x, t), \quad \varphi = \varphi(x, t) = 1, \quad \text{a.e. in } \Omega, \quad \text{a.a. } t,$$

where \mathbf{u} is solution of the Navier-Stokes equations with non-slip boundary condition **explicitly satisfies the weak formulation**

- **This possibility is excluded in the model with constant mobility** since in such model the chemical potential μ (and hence $F'(\varphi)$) appears explicitly

The degenerate vs. the strongly degenerate mobility case

- **If $m'(1) \neq 0$ and $m'(-1) \neq 0$** , then both F and M (s.t. $m(s)M''(s) = 1$, $M(0) = M'(0) = 0$) are bounded in $[-1, 1] \implies$ the conditions $F(\varphi_0) \in L^1(\Omega)$ and $M(\varphi_0) \in L^1(\Omega)$ of Theorem 2 are satisfied by every initial datum φ_0 such that $|\varphi_0| \leq 1$ in $\Omega \implies$ the **existence of pure phases is allowed**

The degenerate vs. the strongly degenerate mobility case

- If $m'(1) \neq 0$ and $m'(-1) \neq 0$, then both F and M (s.t. $m(s)M''(s) = 1$, $M(0) = M'(0) = 0$) are bounded in $[-1, 1] \implies$ the conditions $F(\varphi_0) \in L^1(\Omega)$ and $M(\varphi_0) \in L^1(\Omega)$ of Theorem 2 are satisfied by every initial datum φ_0 such that $|\varphi_0| \leq 1$ in $\Omega \implies$ the **existence of pure phases is allowed**
- If $m'(1) = m'(-1) = 0$ (in this case we say that m is **strongly degenerate**), then it can be proved that the conditions $F(\varphi_0) \in L^1(\Omega)$ and $M(\varphi_0) \in L^1(\Omega)$ imply that the sets $\{x \in \Omega : \varphi_0(x) = 1\}$ and $\{x \in \Omega : \varphi_0(x) = -1\}$ have both measure zero $\implies |\bar{\varphi}_0| < 1$ and furthermore it can be seen that also the sets $\{x \in \Omega : \varphi(x, t) = 1\}$ and $\{x \in \Omega : \varphi(x, t) = -1\}$ have both measure zero for a.a. $t > 0 \implies$ **pure phases are not allowed** (even on subsets of Ω of positive measure)

Theorem 4: The case of more regular chemical potential

(Cf. [Gajewski, Zacharias, '03])

Take the assumptions of Theorem 2 with J such that

$$N_d := \left(\sup_{x \in \Omega} \int_{\Omega} |\nabla J(x - y)|^{\kappa} dy \right)^{1/\kappa} < \infty,$$

where $\kappa = 6/5$ if $d = 3$ and $\kappa > 1$ if $d = 2$.

Theorem 4: The case of more regular chemical potential

(Cf. [Gajewski, Zacharias, '03])

Take the assumptions of Theorem 2 with J such that

$$N_d := \left(\sup_{x \in \Omega} \int_{\Omega} |\nabla J(x-y)|^{\kappa} dy \right)^{1/\kappa} < \infty,$$

where $\kappa = 6/5$ if $d = 3$ and $\kappa > 1$ if $d = 2$. In addition, assume that $F_1 \in C^3(-1, 1)$ and that the following conditions are fulfilled for some $\alpha_0, \beta_0 \geq 0$ and $\rho \in [0, 1)$

$$m(s)F_1''(s) \geq \alpha_0 > 0, \quad |m^2(s)F_1'''(s)| \leq \beta_0, \quad \forall s \in [-1, 1]$$

$$F_1'(s)F_1'''(s) \geq 0 \quad \forall s \in (-1, 1)$$

$$\rho F_1''(s) + F_2''(s) + a(x) \geq 0 \quad \forall s \in (-1, 1), \quad \text{for a.e. } x \in \Omega$$

Let φ_0 be such that

$$F'(\varphi_0) \in L^2(\Omega)$$

Theorem 4: The case of more regular chemical potential

(Cf. [Gajewski, Zacharias, '03])

Take the assumptions of Theorem 2 with J such that

$$N_d := \left(\sup_{x \in \Omega} \int_{\Omega} |\nabla J(x-y)|^{\kappa} dy \right)^{1/\kappa} < \infty,$$

where $\kappa = 6/5$ if $d = 3$ and $\kappa > 1$ if $d = 2$. In addition, assume that $F_1 \in C^3(-1, 1)$ and that the following conditions are fulfilled for some $\alpha_0, \beta_0 \geq 0$ and $\rho \in [0, 1]$

$$\begin{aligned} m(s)F_1''(s) &\geq \alpha_0 > 0, & |m^2(s)F_1'''(s)| &\leq \beta_0, & \forall s \in [-1, 1] \\ F_1'(s)F_1'''(s) &\geq 0 & \forall s \in (-1, 1) \\ \rho F_1''(s) + F_2''(s) + a(x) &\geq 0 & \forall s \in (-1, 1), & \text{ for a.e. } x \in \Omega \end{aligned}$$

Let φ_0 be such that

$$F'(\varphi_0) \in L^2(\Omega)$$

Then, the weak solution $z = [u, \varphi]$ of Theorem 2 satisfies

$$\mu \in L^\infty(0, T; L^2(\Omega)) \quad \nabla \mu \in L^2(0, T; L^2(\Omega))$$

Theorem 4: The case of more regular chemical potential

(Cf. [Gajewski, Zacharias, '03])

Take the assumptions of Theorem 2 with J such that

$$N_d := \left(\sup_{x \in \Omega} \int_{\Omega} |\nabla J(x-y)|^{\kappa} dy \right)^{1/\kappa} < \infty,$$

where $\kappa = 6/5$ if $d = 3$ and $\kappa > 1$ if $d = 2$. In addition, assume that $F_1 \in C^3(-1, 1)$ and that the following conditions are fulfilled for some $\alpha_0, \beta_0 \geq 0$ and $\rho \in [0, 1]$

$$\begin{aligned} m(s)F_1''(s) &\geq \alpha_0 > 0, & |m^2(s)F_1'''(s)| &\leq \beta_0, & \forall s \in [-1, 1] \\ F_1'(s)F_1'''(s) &\geq 0 & \forall s \in (-1, 1) \\ \rho F_1''(s) + F_2''(s) + a(x) &\geq 0 & \forall s \in (-1, 1), & \text{ for a.e. } x \in \Omega \end{aligned}$$

Let φ_0 be such that

$$F'(\varphi_0) \in L^2(\Omega)$$

Then, the weak solution $z = [u, \varphi]$ of Theorem 2 satisfies

$$\mu \in L^\infty(0, T; L^2(\Omega)) \quad \nabla \mu \in L^2(0, T; L^2(\Omega))$$

As a consequence, $z = [u, \varphi]$ now also satisfies the **Definition 1 of weak solutions**, the energy inequality and, for $d = 2$, the energy identity

An idea of the proof

An idea of the proof

Write the weak formulation of approximated the Cahn-Hilliard equation as

$$\begin{aligned} \langle \varphi', \psi \rangle + (m_\varepsilon(\varphi) \nabla(F'_{1\varepsilon}(\varphi)), \nabla \psi) - (m_\varepsilon(\varphi) \nabla(J * \varphi), \nabla \psi) \\ + (m_\varepsilon(\varphi) \nabla(a\varphi + F'_{2\varepsilon}(\varphi)), \nabla \psi) = (\mathbf{u}\varphi, \nabla \psi), \quad \forall \psi \in H^1(\Omega) \end{aligned} \quad (\text{w-CH})$$

An idea of the proof

Write the weak formulation of approximated the Cahn-Hilliard equation as

$$\begin{aligned} \langle \varphi', \psi \rangle + (m_\varepsilon(\varphi) \nabla(F'_{1\varepsilon}(\varphi)), \nabla \psi) - (m_\varepsilon(\varphi) \nabla(J * \varphi), \nabla \psi) \\ + (m_\varepsilon(\varphi) \nabla(a\varphi + F'_{2\varepsilon}(\varphi)), \nabla \psi) = (\mathbf{u}\varphi, \nabla \psi), \quad \forall \psi \in H^1(\Omega) \end{aligned} \quad (\text{w-CH})$$

Take

$$\psi = F'_{1\varepsilon}(\varphi) F''_{1\varepsilon}(\varphi) \in H^1(\Omega)$$

as test function in (w-CH).

An idea of the proof

Write the weak formulation of approximated the Cahn-Hilliard equation as

$$\begin{aligned} \langle \varphi', \psi \rangle + (m_\varepsilon(\varphi) \nabla(F'_{1\varepsilon}(\varphi)), \nabla \psi) - (m_\varepsilon(\varphi) \nabla(J * \varphi), \nabla \psi) \\ + (m_\varepsilon(\varphi) \nabla(a\varphi + F'_{2\varepsilon}(\varphi)), \nabla \psi) = (\mathbf{u}\varphi, \nabla \psi), \quad \forall \psi \in H^1(\Omega) \end{aligned} \quad (\text{w-CH})$$

Take

$$\psi = F'_{1\varepsilon}(\varphi) F''_{1\varepsilon}(\varphi) \in H^1(\Omega)$$

as test function in (w-CH). By the incompressibility condition we deduce

$$\int_{\Omega} (\mathbf{u} \cdot \nabla \varphi) F'_{1\varepsilon}(\varphi) F''_{1\varepsilon}(\varphi) = \int_{\Omega} \mathbf{u} \cdot \nabla \left(\frac{F_{1\varepsilon}^2(\varphi)}{2} \right) = 0$$

An idea of the proof

Write the weak formulation of approximated the Cahn-Hilliard equation as

$$\begin{aligned} \langle \varphi', \psi \rangle + (m_\varepsilon(\varphi) \nabla(F'_{1\varepsilon}(\varphi)), \nabla \psi) - (m_\varepsilon(\varphi) \nabla(J * \varphi), \nabla \psi) \\ + (m_\varepsilon(\varphi) \nabla(a\varphi + F'_{2\varepsilon}(\varphi)), \nabla \psi) = (\mathbf{u}\varphi, \nabla \psi), \quad \forall \psi \in H^1(\Omega) \end{aligned} \quad (\text{w-CH})$$

Take

$$\psi = F'_{1\varepsilon}(\varphi) F''_{1\varepsilon}(\varphi) \in H^1(\Omega)$$

as test function in (w-CH). By the incompressibility condition we deduce

$$\int_{\Omega} (\mathbf{u} \cdot \nabla \varphi) F'_{1\varepsilon}(\varphi) F''_{1\varepsilon}(\varphi) = \int_{\Omega} \mathbf{u} \cdot \nabla \left(\frac{F_{1\varepsilon}^2(\varphi)}{2} \right) = 0$$

Furthermore, by applying a chain rule formula to the convex function $G_\varepsilon := F_{1\varepsilon}^2$, we have

$$\langle \varphi', F'_{1\varepsilon}(\varphi) F''_{1\varepsilon}(\varphi) \rangle = \frac{1}{2} \frac{d}{dt} \int_{\Omega} |F'_{1\varepsilon}(\varphi)|^2$$

An idea of the proof

Write the weak formulation of approximated the Cahn-Hilliard equation as

$$\begin{aligned} \langle \varphi', \psi \rangle + (m_\varepsilon(\varphi) \nabla(F'_{1\varepsilon}(\varphi)), \nabla \psi) - (m_\varepsilon(\varphi) \nabla(J * \varphi), \nabla \psi) \\ + (m_\varepsilon(\varphi) \nabla(a\varphi + F'_{2\varepsilon}(\varphi)), \nabla \psi) = (\mathbf{u}\varphi, \nabla \psi), \quad \forall \psi \in H^1(\Omega) \end{aligned} \quad (\text{w-CH})$$

Take

$$\psi = F'_{1\varepsilon}(\varphi) F''_{1\varepsilon}(\varphi) \in H^1(\Omega)$$

as test function in (w-CH). By the incompressibility condition we deduce

$$\int_{\Omega} (\mathbf{u} \cdot \nabla \varphi) F'_{1\varepsilon}(\varphi) F''_{1\varepsilon}(\varphi) = \int_{\Omega} \mathbf{u} \cdot \nabla \left(\frac{F_{1\varepsilon}^2(\varphi)}{2} \right) = 0$$

Furthermore, by applying a chain rule formula to the convex function $G_\varepsilon := F_{1\varepsilon}^2$, we have

$$\langle \varphi', F'_{1\varepsilon}(\varphi) F''_{1\varepsilon}(\varphi) \rangle = \frac{1}{2} \frac{d}{dt} \int_{\Omega} |F'_{1\varepsilon}(\varphi)|^2$$

Using then the condition $m_\varepsilon F''_{1\varepsilon} \geq \alpha_0$, from the second term in (w-CH), we get

$$\alpha_0 \int_{\Omega} |\nabla F'_{1\varepsilon}(\varphi)|^2 \leq \int_{\Omega} m_\varepsilon(\varphi) F''_{1\varepsilon}(\varphi) |\nabla F_{1\varepsilon}(\varphi)|^2$$

An idea of the proof

Write the weak formulation of approximated the Cahn-Hilliard equation as

$$\begin{aligned} \langle \varphi', \psi \rangle + (m_\varepsilon(\varphi) \nabla(F'_{1\varepsilon}(\varphi)), \nabla \psi) - (m_\varepsilon(\varphi) \nabla(J * \varphi), \nabla \psi) \\ + (m_\varepsilon(\varphi) \nabla(a\varphi + F'_{2\varepsilon}(\varphi)), \nabla \psi) = (\mathbf{u}\varphi, \nabla \psi), \quad \forall \psi \in H^1(\Omega) \end{aligned} \quad (\text{w-CH})$$

Take

$$\psi = F'_{1\varepsilon}(\varphi) F''_{1\varepsilon}(\varphi) \in H^1(\Omega)$$

as test function in (w-CH). By the incompressibility condition we deduce

$$\int_{\Omega} (\mathbf{u} \cdot \nabla \varphi) F'_{1\varepsilon}(\varphi) F''_{1\varepsilon}(\varphi) = \int_{\Omega} \mathbf{u} \cdot \nabla \left(\frac{F_{1\varepsilon}^2(\varphi)}{2} \right) = 0$$

Furthermore, by applying a chain rule formula to the convex function $G_\varepsilon := F_{1\varepsilon}^2$, we have

$$\langle \varphi', F'_{1\varepsilon}(\varphi) F''_{1\varepsilon}(\varphi) \rangle = \frac{1}{2} \frac{d}{dt} \int_{\Omega} |F'_{1\varepsilon}(\varphi)|^2$$

Using then the condition $m_\varepsilon F''_{1\varepsilon} \geq \alpha_0$, from the second term in (w-CH), we get

$$\alpha_0 \int_{\Omega} |\nabla F'_{1\varepsilon}(\varphi)|^2 \leq \int_{\Omega} m_\varepsilon(\varphi) F''_{1\varepsilon}(\varphi) |\nabla F_{1\varepsilon}(\varphi)|^2$$

By means of *some technical arguments* and using the assumptions on F and, in particular, the condition $F'(\varphi_0) \in L^2(\Omega)$, we get

$$F'(\varphi) \in L^\infty(0, T; L^2(\Omega)) \cap L^2(0, T; H^1(\Omega)) \implies \mu \in L^\infty(0, T; L^2(\Omega)) \cap L^2(0, T; H^1(\Omega))$$

Second part: The global attractor in 2D for the degenerate case

Let $\mathbf{d} = 2$ and suppose that the external force is time-independent, i.e. $\mathbf{h} \in H^1(\Omega)_{div}^*$

Second part: The global attractor in 2D for the degenerate case

Let $\mathbf{d} = 2$ and suppose that the external force is time-independent, i.e. $\mathbf{h} \in H^1(\Omega)_{div}^*$

Introduce the set \mathcal{G}_{m_0} of all *weak solutions* (in the sense of **Definition 2**) corresponding to all initial data $\mathbf{z}_0 = [\mathbf{u}_0, \varphi_0] \in \mathcal{X}_{m_0}$, where the phase space \mathcal{X}_{m_0} is the metric space defined by

$$\mathcal{X}_{m_0} := L^2(\Omega)_{div} \times \mathcal{Y}_{m_0}$$

with \mathcal{Y}_{m_0} given by

$$\mathcal{Y}_{m_0} := \{\varphi \in L^\infty(\Omega) : |\varphi| \leq 1 \text{ a.e. in } \Omega, F(\varphi) \in L^1(\Omega), |\overline{\varphi}| \leq m_0\},$$

and $m_0 \in [0, 1]$ is fixed. The metric on \mathcal{X}_{m_0} is

$$d(\mathbf{z}_2, \mathbf{z}_1) := \|\mathbf{u}_2 - \mathbf{u}_1\| + \|\varphi_2 - \varphi_1\|,$$

for every $\mathbf{z}_1 := [\mathbf{u}_1, \varphi_1]$ and $\mathbf{z}_2 := [\mathbf{u}_2, \varphi_2]$ in \mathcal{X}_{m_0} .

Second part: The global attractor in 2D for the degenerate case

Let $\mathbf{d} = 2$ and suppose that the external force is time-independent, i.e. $\mathbf{h} \in H^1(\Omega)_{div}^*$

Introduce the set \mathcal{G}_{m_0} of all *weak solutions* (in the sense of **Definition 2**) corresponding to all initial data $z_0 = [\mathbf{u}_0, \varphi_0] \in \mathcal{X}_{m_0}$, where the phase space \mathcal{X}_{m_0} is the metric space defined by

$$\mathcal{X}_{m_0} := L^2(\Omega)_{div} \times \mathcal{Y}_{m_0}$$

with \mathcal{Y}_{m_0} given by

$$\mathcal{Y}_{m_0} := \{\varphi \in L^\infty(\Omega) : |\varphi| \leq 1 \text{ a.e. in } \Omega, F(\varphi) \in L^1(\Omega), |\overline{\varphi}| \leq m_0\},$$

and $m_0 \in [0, 1]$ is fixed. The metric on \mathcal{X}_{m_0} is

$$d(z_2, z_1) := \|\mathbf{u}_2 - \mathbf{u}_1\| + \|\varphi_2 - \varphi_1\|,$$

for every $z_1 := [\mathbf{u}_1, \varphi_1]$ and $z_2 := [\mathbf{u}_2, \varphi_2]$ in \mathcal{X}_{m_0} . Assume moreover that

(D5) m, F satisfy (A1) and there exists $\alpha_0 > 0$ and $\rho \in [0, 1]$ such that

$$\begin{aligned} m(s)F_1''(s) &\geq \alpha_0, & \forall s \in [-1, 1] \\ \rho F_1''(s) + F_2''(s) + a(x) &\geq 0, & \forall s \in (-1, 1) \text{ a.e. in } \Omega \end{aligned}$$

Existence of the global attractor in 2D

Let $d = 2$, $\mathbf{h} \in H^1(\Omega)_{div}^*$, and suppose that (D2)–(D5) hold.

Existence of the global attractor in 2D

Let $d = 2$, $\mathbf{h} \in H^1(\Omega)_{div}^*$, and suppose that (D2)–(D5) hold. Then

- $\mathcal{G}_{m_0} = \{g : [0, \infty) \rightarrow \mathcal{X}_{m_0}\}$ is a **generalized semiflow on \mathcal{X}_{m_0}** , i.e. a “solution in the sense of Ball” satisfying:

- ▶ existence ($\forall z \in \mathcal{X}_{m_0}$ there exists **at least** one $g \in \mathcal{G}_{m_0}$: $g(0) = z$)
- ▶ translated of solutions are solutions
- ▶ concatenation: if $\phi, \psi \in \mathcal{G}_{m_0}$, $t \geq 0$, with $\psi(0) = \phi(t)$ then $\theta \in \mathcal{G}_{m_0}$ where

$$\theta(\tau) := \begin{cases} \phi(\tau) & \text{for } \tau \in [0, t] \\ \psi(\tau - t) & \text{for } \tau < t \end{cases}$$

- ▶ upper semicontinuity with respect to initial data (if $g_j \in \mathcal{G}_{m_0}$, $g_j(0) \rightarrow z$ then there exists a subsequence g_{j_k} and $g \in \mathcal{G}_{m_0}$ s.t. $g(0) = z$ and $g_{j_k}(t) \rightarrow g(t)$ for each $t \geq 0$)

Existence of the global attractor in 2D

Let $d = 2$, $\mathbf{h} \in H^1(\Omega)_{div}^*$, and suppose that (D2)–(D5) hold. Then

- $\mathcal{G}_{m_0} = \{g : [0, \infty) \rightarrow \mathcal{X}_{m_0}\}$ is a **generalized semiflow on \mathcal{X}_{m_0}** , i.e. a “solution in the sense of Ball” satisfying:

- ▶ existence ($\forall z \in \mathcal{X}_{m_0}$ there exists **at least** one $g \in \mathcal{G}_{m_0}$: $g(0) = z$)
- ▶ translated of solutions are solutions
- ▶ concatenation: if $\phi, \psi \in \mathcal{G}_{m_0}$, $t \geq 0$, with $\psi(0) = \phi(t)$ then $\theta \in \mathcal{G}_{m_0}$ where

$$\theta(\tau) := \begin{cases} \phi(\tau) & \text{for } \tau \in [0, t] \\ \psi(\tau - t) & \text{for } \tau < t \end{cases}$$

- ▶ upper semicontinuity with respect to initial data (if $g_j \in \mathcal{G}_{m_0}$, $g_j(0) \rightarrow z$ then there exists a subsequence g_{j_k} and $g \in \mathcal{G}_{m_0}$ s.t. $g(0) = z$ and $g_{j_k}(t) \rightarrow g(t)$ for each $t \geq 0$)
- \mathcal{G}_{m_0} is **point dissipative** (there is a bdd set B_0 such that for any $g \in \mathcal{G}_{m_0}$ $g(t) \in B_0$ for t sufficiently large),

Existence of the global attractor in 2D

Let $d = 2$, $\mathbf{h} \in H^1(\Omega)_{div}^*$, and suppose that (D2)–(D5) hold. Then

- $\mathcal{G}_{m_0} = \{g : [0, \infty) \rightarrow \mathcal{X}_{m_0}\}$ is a **generalized semiflow on \mathcal{X}_{m_0}** , i.e. a “solution in the sense of Ball” satisfying:

- ▶ existence ($\forall z \in \mathcal{X}_{m_0}$ there exists **at least** one $g \in \mathcal{G}_{m_0}$: $g(0) = z$)
- ▶ translated of solutions are solutions
- ▶ concatenation: if $\phi, \psi \in \mathcal{G}_{m_0}$, $t \geq 0$, with $\psi(0) = \phi(t)$ then $\theta \in \mathcal{G}_{m_0}$ where

$$\theta(\tau) := \begin{cases} \phi(\tau) & \text{for } \tau \in [0, t] \\ \psi(\tau - t) & \text{for } \tau < t \end{cases}$$

- ▶ upper semicontinuity with respect to initial data (if $g_j \in \mathcal{G}_{m_0}$, $g_j(0) \rightarrow z$ then there exists a subsequence g_{j_k} and $g \in \mathcal{G}_{m_0}$ s.t. $g(0) = z$ and $g_{j_k}(t) \rightarrow g(t)$ for each $t \geq 0$)
- \mathcal{G}_{m_0} is **point dissipative** (there is a bdd set B_0 such that for any $g \in \mathcal{G}_{m_0}$ $g(t) \in B_0$ for t sufficiently large), **eventually bounded** (given any bdd $B \subset \mathcal{X}_{m_0}$ there exists $\tau \geq 0$ with $g^\tau(B)$ bdd, with $g^\tau(t) := g(t + \tau)$),

Existence of the global attractor in 2D

Let $d = 2$, $\mathbf{h} \in H^1(\Omega)_{div}^*$, and suppose that (D2)–(D5) hold. Then

- $\mathcal{G}_{m_0} = \{g : [0, \infty) \rightarrow \mathcal{X}_{m_0}\}$ is a **generalized semiflow on \mathcal{X}_{m_0}** , i.e. a “solution in the sense of Ball” satisfying:

- ▶ existence ($\forall z \in \mathcal{X}_{m_0}$ there exists **at least** one $g \in \mathcal{G}_{m_0}$: $g(0) = z$)
- ▶ translated of solutions are solutions
- ▶ concatenation: if $\phi, \psi \in \mathcal{G}_{m_0}$, $t \geq 0$, with $\psi(0) = \phi(t)$ then $\theta \in \mathcal{G}_{m_0}$ where

$$\theta(\tau) := \begin{cases} \phi(\tau) & \text{for } \tau \in [0, t] \\ \psi(\tau - t) & \text{for } t < \tau \end{cases}$$

- ▶ upper semicontinuity with respect to initial data (if $g_j \in \mathcal{G}_{m_0}$, $g_j(0) \rightarrow z$ then there exists a subsequence g_{j_k} and $g \in \mathcal{G}_{m_0}$ s.t. $g(0) = z$ and $g_{j_k}(t) \rightarrow g(t)$ for each $t \geq 0$)
- \mathcal{G}_{m_0} is **point dissipative** (there is a bdd set B_0 such that for any $g \in \mathcal{G}_{m_0}$ $g(t) \in B_0$ for t sufficiently large), **eventually bounded** (given any bdd $B \subset \mathcal{X}_{m_0}$ there exists $\tau \geq 0$ with $g^\tau(B)$ bdd, with $g^\tau(t) := g(t + \tau)$), and **compact**

Existence of the global attractor in 2D

Let $d = 2$, $\mathbf{h} \in H^1(\Omega)_{div}^*$, and suppose that (D2)–(D5) hold. Then

- $\mathcal{G}_{m_0} = \{g : [0, \infty) \rightarrow \mathcal{X}_{m_0}\}$ is a **generalized semiflow on \mathcal{X}_{m_0}** , i.e. a “solution in the sense of Ball” satisfying:

- ▶ existence ($\forall z \in \mathcal{X}_{m_0}$ there exists **at least** one $g \in \mathcal{G}_{m_0}$: $g(0) = z$)
- ▶ translated of solutions are solutions
- ▶ concatenation: if $\phi, \psi \in \mathcal{G}_{m_0}$, $t \geq 0$, with $\psi(0) = \phi(t)$ then $\theta \in \mathcal{G}_{m_0}$ where

$$\theta(\tau) := \begin{cases} \phi(\tau) & \text{for } \tau \in [0, t] \\ \psi(\tau - t) & \text{for } \tau < t \end{cases}$$

- ▶ upper semicontinuity with respect to initial data (if $g_j \in \mathcal{G}_{m_0}$, $g_j(0) \rightarrow z$ then there exists a subsequence g_{j_k} and $g \in \mathcal{G}_{m_0}$ s.t. $g(0) = z$ and $g_{j_k}(t) \rightarrow g(t)$ for each $t \geq 0$)
- \mathcal{G}_{m_0} is **point dissipative** (there is a bdd set B_0 such that for any $g \in \mathcal{G}_{m_0}$ $g(t) \in B_0$ for t sufficiently large), **eventually bounded** (given any bdd $B \subset \mathcal{X}_{m_0}$ there exists $\tau \geq 0$ with $g^\tau(B)$ bdd, with $g^\tau(t) := g(t + \tau)$), and **compact**
- As a consequence of [Ball, '97&'98], we have: \mathcal{G}_{m_0} **possesses a global attractor** (compact, invariant set that *attracts* all bounded sets)

Existence of the global attractor in 2D

Let $d = 2$, $\mathbf{h} \in H^1(\Omega)_{div}^*$, and suppose that (D2)–(D5) hold. Then

- $\mathcal{G}_{m_0} = \{g : [0, \infty) \rightarrow \mathcal{X}_{m_0}\}$ is a **generalized semiflow on \mathcal{X}_{m_0}** , i.e. a “solution in the sense of Ball” satisfying:

- ▶ existence ($\forall z \in \mathcal{X}_{m_0}$ there exists **at least** one $g \in \mathcal{G}_{m_0}$: $g(0) = z$)
- ▶ translated of solutions are solutions
- ▶ concatenation: if $\phi, \psi \in \mathcal{G}_{m_0}$, $t \geq 0$, with $\psi(0) = \phi(t)$ then $\theta \in \mathcal{G}_{m_0}$ where

$$\theta(\tau) := \begin{cases} \phi(\tau) & \text{for } \tau \in [0, t] \\ \psi(\tau - t) & \text{for } \tau < t \end{cases}$$

- ▶ upper semicontinuity with respect to initial data (if $g_j \in \mathcal{G}_{m_0}$, $g_j(0) \rightarrow z$ then there exists a subsequence g_{j_k} and $g \in \mathcal{G}_{m_0}$ s.t. $g(0) = z$ and $g_{j_k}(t) \rightarrow g(t)$ for each $t \geq 0$)
- \mathcal{G}_{m_0} is **point dissipative** (there is a bdd set B_0 such that for any $g \in \mathcal{G}_{m_0}$ $g(t) \in B_0$ for t sufficiently large), **eventually bounded** (given any bdd $B \subset \mathcal{X}_{m_0}$ there exists $\tau \geq 0$ with $g^\tau(B)$ bdd, with $g^\tau(t) := g(t + \tau)$), and **compact**
- As a consequence of [Ball, '97&'98], we have: \mathcal{G}_{m_0} **possesses a global attractor** (compact, invariant set that *attracts* all bounded sets)

We point out that the existence of the global attractor is established **without the restriction $|\bar{\varphi}| < 1$ on the generalized semiflow**. In particular, this result does not require the separation property

An idea of the proof

An idea of the proof

1) Upper semicontinuity with respect to initial data:

An idea of the proof

1) Upper semicontinuity with respect to initial data: take then $z_j = [\mathbf{u}_j, \varphi_j] \in \mathcal{G}_{m_0}$ such that $z_j(0) \rightarrow z_0$ in \mathcal{X}_{m_0} . Our aim is to prove that

$\exists z \in \mathcal{G}_{m_0}$ with $z(0) = z_0$ and a subsequence $\{z_{j_k}\} : z_{j_k}(t) \rightarrow z(t)$ in \mathcal{X}_{m_0} for all $t \geq 0$

An idea of the proof

1) Upper semicontinuity with respect to initial data: take then $z_j = [\mathbf{u}_j, \varphi_j] \in \mathcal{G}_{m_0}$ such that $z_j(0) \rightarrow z_0$ in \mathcal{X}_{m_0} . Our aim is to prove that

$\exists z \in \mathcal{G}_{m_0}$ with $z(0) = z_0$ and a subsequence $\{z_{j_k}\} : z_{j_k}(t) \rightarrow z(t)$ in \mathcal{X}_{m_0} for all $t \geq 0$

Each weak solution $z_j = [\mathbf{u}_j, \varphi_j]$ satisfies the energy equation which implies

$$\frac{d}{dt} \left(\|\mathbf{u}_j\|^2 + \|\varphi_j\|^2 \right) + (1 - \rho)\alpha_0 \|\nabla \varphi_j\|^2 + \nu \|\nabla \mathbf{u}_j\|^2 \leq c + c\|\mathbf{u}_j\|^2 + \frac{1}{2\nu} \|\mathbf{h}\|_{H^1(\Omega)_{div}^*}^2,$$

An idea of the proof

1) Upper semicontinuity with respect to initial data: take then $z_j = [\mathbf{u}_j, \varphi_j] \in \mathcal{G}_{m_0}$ such that $z_j(0) \rightarrow z_0$ in \mathcal{X}_{m_0} . Our aim is to prove that

$\exists z \in \mathcal{G}_{m_0}$ with $z(0) = z_0$ and a subsequence $\{z_{j_k}\} : z_{j_k}(t) \rightarrow z(t)$ in \mathcal{X}_{m_0} for all $t \geq 0$

Each weak solution $z_j = [\mathbf{u}_j, \varphi_j]$ satisfies the energy equation which implies

$$\frac{d}{dt} \left(\|\mathbf{u}_j\|^2 + \|\varphi_j\|^2 \right) + (1 - \rho)\alpha_0 \|\nabla \varphi_j\|^2 + \nu \|\nabla \mathbf{u}_j\|^2 \leq c + c\|\mathbf{u}_j\|^2 + \frac{1}{2\nu} \|\mathbf{h}\|_{H^1(\Omega)_{div}^*}^2,$$

By comparison, we also get $\|\mathbf{u}'_j\|_{L^2(0,T;H^1(\Omega)_{div}^*)}, \|\varphi'_j\|_{L^2(0,T;H^1(\Omega)^*)} \leq C$

An idea of the proof

1) Upper semicontinuity with respect to initial data: take then $z_j = [\mathbf{u}_j, \varphi_j] \in \mathcal{G}_{m_0}$ such that $z_j(0) \rightarrow z_0$ in \mathcal{X}_{m_0} . Our aim is to prove that

$\exists z \in \mathcal{G}_{m_0}$ with $z(0) = z_0$ and a subsequence $\{z_{j_k}\} : z_{j_k}(t) \rightarrow z(t)$ in \mathcal{X}_{m_0} for all $t \geq 0$

Each weak solution $z_j = [\mathbf{u}_j, \varphi_j]$ satisfies the energy equation which implies

$$\frac{d}{dt} \left(\|\mathbf{u}_j\|^2 + \|\varphi_j\|^2 \right) + (1 - \rho)\alpha_0 \|\nabla \varphi_j\|^2 + \nu \|\nabla \mathbf{u}_j\|^2 \leq c + c\|\mathbf{u}_j\|^2 + \frac{1}{2\nu} \|\mathbf{h}\|_{H^1(\Omega)_{div}^*}^2,$$

By comparison, we also get $\|\mathbf{u}'_j\|_{L^2(0,T;H^1(\Omega)_{div}^*)}, \|\varphi'_j\|_{L^2(0,T;H^1(\Omega)^*)} \leq C$ and hence **for a.e. $t \geq 0$**

$$\mathbf{u}_j(t) \rightarrow \mathbf{u}(t) \quad \text{strongly in } L^2(\Omega)_{div}$$

$$\varphi_j(t) \rightarrow \varphi(t) \quad \text{strongly in } L^2(\Omega)$$

An idea of the proof

1) Upper semicontinuity with respect to initial data: take then $z_j = [\mathbf{u}_j, \varphi_j] \in \mathcal{G}_{m_0}$ such that $z_j(0) \rightarrow z_0$ in \mathcal{X}_{m_0} . Our aim is to prove that

$\exists z \in \mathcal{G}_{m_0}$ with $z(0) = z_0$ and a subsequence $\{z_{j_k}\} : z_{j_k}(t) \rightarrow z(t)$ in \mathcal{X}_{m_0} for all $t \geq 0$

Each weak solution $z_j = [\mathbf{u}_j, \varphi_j]$ satisfies the energy equation which implies

$$\frac{d}{dt} \left(\|\mathbf{u}_j\|^2 + \|\varphi_j\|^2 \right) + (1 - \rho)\alpha_0 \|\nabla \varphi_j\|^2 + \nu \|\nabla \mathbf{u}_j\|^2 \leq c + c\|\mathbf{u}_j\|^2 + \frac{1}{2\nu} \|\mathbf{h}\|_{H^1(\Omega)_{div}^*}^2,$$

By comparison, we also get $\|\mathbf{u}'_j\|_{L^2(0,T;H^1(\Omega)_{div}^*)}, \|\varphi'_j\|_{L^2(0,T;H^1(\Omega)^*)} \leq C$ and hence **for a.e. $t \geq 0$**

$$\mathbf{u}_j(t) \rightarrow \mathbf{u}(t) \quad \text{strongly in } L^2(\Omega)_{div}$$

$$\varphi_j(t) \rightarrow \varphi(t) \quad \text{strongly in } L^2(\Omega)$$

By standard compactness results, we deduce that $z := [\mathbf{u}, \varphi] \in \mathcal{G}_{m_0}$ and $z(0) = z_0$. We can also see that $z_j(t) \rightarrow z(t)$ in \mathcal{X}_{m_0} **for all $t \geq 0$** by using the energy equality and the continuity in $[0, \infty)$ of $E(z(t)) = \|\mathbf{u}(t)\|^2 + \|\varphi(t)\|^2$.

An idea of the proof

1) Upper semicontinuity with respect to initial data: take then $z_j = [\mathbf{u}_j, \varphi_j] \in \mathcal{G}_{m_0}$ such that $z_j(0) \rightarrow z_0$ in \mathcal{X}_{m_0} . Our aim is to prove that

$\exists z \in \mathcal{G}_{m_0}$ with $z(0) = z_0$ and a subsequence $\{z_{j_k}\} : z_{j_k}(t) \rightarrow z(t)$ in \mathcal{X}_{m_0} for all $t \geq 0$

Each weak solution $z_j = [\mathbf{u}_j, \varphi_j]$ satisfies the energy equation which implies

$$\frac{d}{dt} \left(\|\mathbf{u}_j\|^2 + \|\varphi_j\|^2 \right) + (1 - \rho)\alpha_0 \|\nabla \varphi_j\|^2 + \nu \|\nabla \mathbf{u}_j\|^2 \leq c + c\|\mathbf{u}_j\|^2 + \frac{1}{2\nu} \|\mathbf{h}\|_{H^1(\Omega)_{div}^*}^2,$$

By comparison, we also get $\|\mathbf{u}'_j\|_{L^2(0, T; H^1(\Omega)_{div}^*)}, \|\varphi'_j\|_{L^2(0, T; H^1(\Omega)^*)} \leq C$ and hence **for a.e. $t \geq 0$**

$$\mathbf{u}_j(t) \rightarrow \mathbf{u}(t) \quad \text{strongly in } L^2(\Omega)_{div}$$

$$\varphi_j(t) \rightarrow \varphi(t) \quad \text{strongly in } L^2(\Omega)$$

By standard compactness results, we deduce that $z := [\mathbf{u}, \varphi] \in \mathcal{G}_{m_0}$ and $z(0) = z_0$. We can also see that $z_j(t) \rightarrow z(t)$ in \mathcal{X}_{m_0} **for all $t \geq 0$** by using the energy equality and the continuity in $[0, \infty)$ of $E(z(t)) = \|\mathbf{u}(t)\|^2 + \|\varphi(t)\|^2$.

2) Dissipativity and eventual boundedness: From the energy identity and by means of Poincaré inequality we get

$$\frac{d}{dt} \left(\|\mathbf{u}\|^2 + \|\varphi - \bar{\varphi}_0\|^2 \right) + (1 - \rho)\alpha_0 C_P \|\varphi - \bar{\varphi}_0\|^2 + \nu \lambda_1 \|\mathbf{u}\|^2 \leq C_2 + \frac{1}{\nu} \|\mathbf{h}\|_{H^1(\Omega)_{div}'}^2$$

An idea of the proof

1) Upper semicontinuity with respect to initial data: take then $z_j = [\mathbf{u}_j, \varphi_j] \in \mathcal{G}_{m_0}$ such that $z_j(0) \rightarrow z_0$ in \mathcal{X}_{m_0} . Our aim is to prove that

$\exists z \in \mathcal{G}_{m_0}$ with $z(0) = z_0$ and a subsequence $\{z_{j_k}\} : z_{j_k}(t) \rightarrow z(t)$ in \mathcal{X}_{m_0} for all $t \geq 0$

Each weak solution $z_j = [\mathbf{u}_j, \varphi_j]$ satisfies the energy equation which implies

$$\frac{d}{dt} \left(\|\mathbf{u}_j\|^2 + \|\varphi_j\|^2 \right) + (1 - \rho)\alpha_0 \|\nabla \varphi_j\|^2 + \nu \|\nabla \mathbf{u}_j\|^2 \leq c + c\|\mathbf{u}_j\|^2 + \frac{1}{2\nu} \|\mathbf{h}\|_{H^1(\Omega)_{div}^*}^2,$$

By comparison, we also get $\|\mathbf{u}'_j\|_{L^2(0,T;H^1(\Omega)_{div}^*)}, \|\varphi'_j\|_{L^2(0,T;H^1(\Omega)^*)} \leq C$ and hence **for a.e. $t \geq 0$**

$$\mathbf{u}_j(t) \rightarrow \mathbf{u}(t) \quad \text{strongly in } L^2(\Omega)_{div}$$

$$\varphi_j(t) \rightarrow \varphi(t) \quad \text{strongly in } L^2(\Omega)$$

By standard compactness results, we deduce that $z := [\mathbf{u}, \varphi] \in \mathcal{G}_{m_0}$ and $z(0) = z_0$. We can also see that $z_j(t) \rightarrow z(t)$ in \mathcal{X}_{m_0} **for all $t \geq 0$** by using the energy equality and the continuity in $[0, \infty)$ of $E(z(t)) = \|\mathbf{u}(t)\|^2 + \|\varphi(t)\|^2$.

2) Dissipativity and eventual boundedness: From the energy identity and by means of Poincaré inequality we get

$$\frac{d}{dt} (\|\mathbf{u}\|^2 + \|\varphi - \bar{\varphi}_0\|^2) + (1 - \rho)\alpha_0 C_P \|\varphi - \bar{\varphi}_0\|^2 + \nu \lambda_1 \|\mathbf{u}\|^2 \leq C_2 + \frac{1}{\nu} \|\mathbf{h}\|_{H^1(\Omega)_{div}'}^2$$

This estimate easily yields

$$d^2(z(t), 0) \leq d^2(z_0, 0) e^{-\eta t} + \frac{2C_3}{\eta} + |\bar{\varphi}_0|^2 |\Omega|, \quad \forall t \geq 0$$

where $d(z_2, z_1) := \|\mathbf{u}_2 - \mathbf{u}_1\| + \|\varphi_2 - \varphi_1\|$

Third part: The convective nonlocal Cahn-Hilliard equation with degenerate mobility

Assume that (D1)–(D4) are satisfied. Let $\mathbf{u} \in L^2_{loc}([0, \infty); H^1(\Omega)_{div} \cap L^\infty(\Omega)^d)$ be given and let $\mathbf{h} \in H^1(\Omega)_{div}^*$, $\varphi_0 \in L^\infty(\Omega)$ such that $F(\varphi_0) \in L^1(\Omega)$ and $M(\varphi_0) \in L^1(\Omega)$

Third part: The convective nonlocal Cahn-Hilliard equation with degenerate mobility

Assume that (D1)–(D4) are satisfied. Let $\mathbf{u} \in L^2_{loc}([0, \infty); H^1(\Omega)_{div} \cap L^\infty(\Omega)^d)$ be given and let $\mathbf{h} \in H^1(\Omega)_{div}^*$, $\varphi_0 \in L^\infty(\Omega)$ such that $F(\varphi_0) \in L^1(\Omega)$ and $M(\varphi_0) \in L^1(\Omega)$

Then, for every $T > 0$ there exists a weak solution φ to

$$\begin{aligned} \langle \varphi_t, \psi \rangle + \int_{\Omega} m(\varphi) F''(\varphi) \nabla \varphi \cdot \nabla \psi + \int_{\Omega} m(\varphi) a \nabla \varphi \cdot \nabla \psi \\ + \int_{\Omega} m(\varphi) (\varphi \nabla a - \nabla J * \varphi) \cdot \nabla \psi = (\mathbf{u} \varphi, \nabla \psi) \end{aligned}$$

and such that $\overline{\varphi}(t) = \overline{\varphi_0}$ for all $t \in [0, T]$

Third part: The convective nonlocal Cahn-Hilliard equation with degenerate mobility

Assume that (D1)–(D4) are satisfied. Let $\mathbf{u} \in L^2_{loc}([0, \infty); H^1(\Omega)_{div} \cap L^\infty(\Omega)^d)$ be given and let $\mathbf{h} \in H^1(\Omega)^*_{div}$, $\varphi_0 \in L^\infty(\Omega)$ such that $F(\varphi_0) \in L^1(\Omega)$ and $M(\varphi_0) \in L^1(\Omega)$

Then, for every $T > 0$ there exists a weak solution φ to

$$\begin{aligned} \langle \varphi_t, \psi \rangle + \int_{\Omega} m(\varphi) F''(\varphi) \nabla \varphi \cdot \nabla \psi + \int_{\Omega} m(\varphi) \mathbf{a} \nabla \varphi \cdot \nabla \psi \\ + \int_{\Omega} m(\varphi) (\varphi \nabla \mathbf{a} - \nabla J * \varphi) \cdot \nabla \psi = (\mathbf{u} \varphi, \nabla \psi) \end{aligned}$$

and such that $\overline{\varphi}(t) = \overline{\varphi_0}$ for all $t \in [0, T]$

Furthermore, $\varphi \in L^\infty(0, T; L^p(\Omega))$, where $p \leq 6$ for $d = 3$ and $2 \leq p < \infty$ for $d = 2$. In addition, the following energy identity holds

$$\frac{1}{2} \frac{d}{dt} \|\varphi\|^2 + \int_{\Omega} m(\varphi) F''(\varphi) |\nabla \varphi|^2 + \int_{\Omega} \mathbf{a} m(\varphi) |\nabla \varphi|^2 + \int_{\Omega} m(\varphi) (\varphi \nabla \mathbf{a} - \nabla J * \varphi) \cdot \nabla \varphi = 0$$

for a.a. $t > 0$ and in $\mathcal{D}'(0, \infty)$

The convective nonlocal Cahn-Hilliard equation: uniqueness and attractor

Let the hypotheses of the previous Theorem be satisfied and the following conditions (cf. **(D5)**) are fulfilled for some $\alpha_0 > 0$ and $\rho \in [0, 1]$

$$\begin{aligned} m(s)F_1''(s) &\geq \alpha_0 > 0 \quad \forall s \in [-1, 1] \\ \rho F_1''(s) + F_2''(s) + a(x) &\geq 0 \quad \forall s \in (-1, 1), \quad \text{for a.e. } x \in \Omega \end{aligned}$$

The convective nonlocal Cahn-Hilliard equation: uniqueness and attractor

Let the hypotheses of the previous Theorem be satisfied and the following conditions (cf. **(D5)**) are fulfilled for some $\alpha_0 > 0$ and $\rho \in [0, 1]$

$$\begin{aligned} m(s)F_1''(s) &\geq \alpha_0 > 0 \quad \forall s \in [-1, 1] \\ \rho F_1''(s) + F_2''(s) + a(x) &\geq 0 \quad \forall s \in (-1, 1), \quad \text{for a.e. } x \in \Omega \end{aligned}$$

Then, **the weak solution is unique.**

The convective nonlocal Cahn-Hilliard equation: uniqueness and attractor

Let the hypotheses of the previous Theorem be satisfied and the following conditions (cf. **(D5)**) are fulfilled for some $\alpha_0 > 0$ and $\rho \in [0, 1]$

$$\begin{aligned} m(s)F_1''(s) &\geq \alpha_0 > 0 \quad \forall s \in [-1, 1] \\ \rho F_1''(s) + F_2''(s) + a(x) &\geq 0 \quad \forall s \in (-1, 1), \quad \text{for a.e. } x \in \Omega \end{aligned}$$

Then, **the weak solution is unique.**

Hence, we can define a semiflow $S(t)$ on \mathcal{Y}_{m_0} , $m_0 \in [0, 1]$, endowed with the metric induced by the L^2 -norm.

The convective nonlocal Cahn-Hilliard equation: uniqueness and attractor

Let the hypotheses of the previous Theorem be satisfied and the following conditions (cf. **(D5)**) are fulfilled for some $\alpha_0 > 0$ and $\rho \in [0, 1]$

$$\begin{aligned} m(s)F_1''(s) &\geq \alpha_0 > 0 \quad \forall s \in [-1, 1] \\ \rho F_1''(s) + F_2''(s) + a(x) &\geq 0 \quad \forall s \in (-1, 1), \quad \text{for a.e. } x \in \Omega \end{aligned}$$

Then, **the weak solution is unique.**

Hence, we can define a semiflow $S(t)$ on \mathcal{Y}_{m_0} , $m_0 \in [0, 1]$, endowed with the metric induced by the L^2 -norm.

It is then immediate to check that the arguments used in the proofs of the previous results can be adapted to the present situation. Hence we have that: given $\mathbf{u} \in L^\infty(\Omega)^d$ independent of time, then, **the dynamical system $(\mathcal{Y}_{m_0}, S(t))$ possesses a connected global attractor**

Note that: up to our knowledge **uniqueness of solutions is an open issue** for the local case as well as for the complete nonlocal system including Navier-Stokes even in dimension two.

An idea of the proof of uniqueness

An idea of the proof of uniqueness

Rewrite the Cahn-Hilliard equation as

$$\langle \varphi_t, \psi \rangle + (\nabla \Lambda(\cdot, \varphi), \nabla \psi) - (\Gamma(\varphi) \nabla a, \nabla \psi) + (m(\varphi)(\varphi \nabla a - \nabla J * \varphi), \nabla \psi) = (\mathbf{u} \varphi, \nabla \psi),$$

for all $\psi \in H^1(\Omega)$, where $\Lambda(x, s) := \Lambda_1(s) + \Lambda_2(s) + a(x)\Gamma(s)$ and

$$\Lambda_1(s) := \int_0^s m(\sigma) F_1''(\sigma) d\sigma, \quad \Lambda_2(s) := \int_0^s m(\sigma) F_2''(\sigma) d\sigma, \quad \Gamma(s) := \int_0^s m(\sigma) d\sigma,$$

for all $s \in [-1, 1]$.

An idea of the proof of uniqueness

Rewrite the Cahn-Hilliard equation as

$$\langle \varphi_t, \psi \rangle + (\nabla \Lambda(\cdot, \varphi), \nabla \psi) - (\Gamma(\varphi) \nabla a, \nabla \psi) + (m(\varphi)(\varphi \nabla a - \nabla J * \varphi), \nabla \psi) = (\mathbf{u} \varphi, \nabla \psi),$$

for all $\psi \in H^1(\Omega)$, where $\Lambda(x, s) := \Lambda_1(s) + \Lambda_2(s) + a(x)\Gamma(s)$ and

$$\Lambda_1(s) := \int_0^s m(\sigma) F_1''(\sigma) d\sigma, \quad \Lambda_2(s) := \int_0^s m(\sigma) F_2''(\sigma) d\sigma, \quad \Gamma(s) := \int_0^s m(\sigma) d\sigma,$$

for all $s \in [-1, 1]$. Take the difference between the two identities, set $\varphi := \varphi_1 - \varphi_2$ and $\psi = \mathcal{N}\varphi$ (notice that $\bar{\varphi} = 0$):

$$\begin{aligned} & \frac{1}{2} \frac{d}{dt} \|\mathcal{N}^{1/2} \varphi\|^2 + (\Lambda(\varphi_2) - \Lambda(\varphi_1), \varphi) - ((\Gamma(\varphi_2) - \Gamma(\varphi_1)) \nabla a, \nabla \mathcal{N}\varphi) \\ & + ((m(\varphi_2) - m(\varphi_1))(\varphi_2 \nabla a - \nabla J * \varphi_2) + m(\varphi_1)(\varphi \nabla a - \nabla J * \varphi), \nabla \mathcal{N}\varphi) \\ & = (\mathbf{u} \varphi, \nabla \mathcal{N}\varphi) \end{aligned}$$

An idea of the proof of uniqueness

Rewrite the Cahn-Hilliard equation as

$$\langle \varphi_t, \psi \rangle + (\nabla \Lambda(\cdot, \varphi), \nabla \psi) - (\Gamma(\varphi) \nabla a, \nabla \psi) + (m(\varphi)(\varphi \nabla a - \nabla J * \varphi), \nabla \psi) = (\mathbf{u} \varphi, \nabla \psi),$$

for all $\psi \in H^1(\Omega)$, where $\Lambda(x, s) := \Lambda_1(s) + \Lambda_2(s) + a(x)\Gamma(s)$ and

$$\Lambda_1(s) := \int_0^s m(\sigma) F_1''(\sigma) d\sigma, \quad \Lambda_2(s) := \int_0^s m(\sigma) F_2''(\sigma) d\sigma, \quad \Gamma(s) := \int_0^s m(\sigma) d\sigma,$$

for all $s \in [-1, 1]$. Take the difference between the two identities, set $\varphi := \varphi_1 - \varphi_2$ and $\psi = \mathcal{N}\varphi$ (notice that $\bar{\varphi} = 0$):

$$\begin{aligned} & \frac{1}{2} \frac{d}{dt} \|\mathcal{N}^{1/2} \varphi\|^2 + (\Lambda(\varphi_2) - \Lambda(\varphi_1), \varphi) - ((\Gamma(\varphi_2) - \Gamma(\varphi_1)) \nabla a, \nabla \mathcal{N}\varphi) \\ & + ((m(\varphi_2) - m(\varphi_1))(\varphi_2 \nabla a - \nabla J * \varphi_2) + m(\varphi_1)(\varphi \nabla a - \nabla J * \varphi), \nabla \mathcal{N}\varphi) \\ & = (\mathbf{u} \varphi, \nabla \mathcal{N}\varphi) \end{aligned}$$

On account of $m(s)F_1''(s) \geq \alpha_0 > 0$, $\rho F_1''(s) + F_2''(s) + a(x) \geq 0$, we find

$$\begin{aligned} (\Lambda(\cdot, \varphi_2) - \Lambda(\cdot, \varphi_1), \varphi) & \geq (1 - \rho) \int_{\Omega} m(\theta \varphi_2 + (1 - \theta) \varphi_1) F_1''(\theta \varphi_2 + (1 - \theta) \varphi_1) \varphi^2 \\ & \geq (1 - \rho) \alpha_0 \|\varphi\|^2 \end{aligned}$$

and the other terms can be estimated in order to apply Gronwall.

Conclusions

Conclusions

We have proved in [Frigeri, Grasselli, E.R., preprint arXiv:1303.6446, 2013]

- Existence of solutions for the nonlocal 3D Navier-Stokes Cahn-Hilliard model with nondegenerate and with degenerate mobility
- Existence of the attractor in the 2D case
- Well-posedness and existence of the attractor for the 3D nonlocal convective Cahn-Hilliard equation

Conclusions

We have proved in [Frigeri, Grasselli, E.R., preprint arXiv:1303.6446, 2013]

- Existence of solutions for the nonlocal 3D Navier-Stokes Cahn-Hilliard model with nondegenerate and with degenerate mobility
- Existence of the attractor in the 2D case
- Well-posedness and existence of the attractor for the 3D nonlocal convective Cahn-Hilliard equation

There are still a lot of open problems like

- The case of non-smooth potentials like $F(\varphi) = I_{[-1,1]}(\varphi)$
- The case of unmatched densities (cf. [Abels, Depner, Garcke, 2013] for the local case) or of compressible fluids (cf. [Abels, Feireisl, 2008] for the local case)
- The non isothermal case (cf. [Eleuteri, E.R., Schimperna, work in progress] for the local case)
- ...

Thanks for your attention!

cf. <http://www.mat.unimi.it/users/rocca/>

Some comparisons with other results: local vs nonlocal

Results	Local CH	Nonlocal CH	Local CHNS	Nonlocal CHNS
Uniqueness	<p>3D: True for non-degenerate mobility (e.g. [Elliott, '89, Novick Cohen, '9, [Elliott, Luckhaus, '91])</p> <p>Open for degenerate mobility and singular potential</p>	<p>3D: True for constant mobility (e.g. [Colli, Krejčí, E.R., Sprekels, '04])</p> <p>3D: True for degenerate mobility and singular potential [Gajewski, Zacharias, '03, [Grasselli, Frigeri, E.R., '13]</p>	<p>2D: True for nondegenerate mobility [Abels, '09, Boyer, '99]</p> <p>Open for degenerate mobility and singular potential</p>	<p>Open even in 2D</p> <p>Open even in 2D</p>
Separation	<p>2D: True with logarithmic potential and constant mobility [Miranville, Zelik, '04] , 3D: Open for the logarithmic potential</p>	<p>3D: true for degenerate mobility and singular potential [Londen, Petzeltová, '11]</p>	<p>Open</p>	<p>3D: true for degenerate mobility and singular potential</p>